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Kyas, M.

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Summary

Embedded real-time systems are small computer systems which are used to control an increasing number of devices in every-day life. They are embedded in, for example, DVD players, microwave ovens, antilock braking systems, and autopilots. It is important that these devices always perform their function correctly in case the life of people depends upon the software used in them. Moreover, high costs are usually involved in recalling defective devices, for example, in cars. Therefore, it is desirable that these systems are formally validated, that is, a *proof* of the correct functioning of the system is constructed. Such a proof is especially important for real-time systems, because they not only need to function correctly, but also deliver their reactions *on time*. For example, an air-bag should not only inflate when a car crashes, but it should inflate milliseconds after the impact, and not seconds.

Ever since the first embedded systems were developed, their complexity has been steadily increasing. In order to control and understand this complexity different methods are used to describe the structure, the behaviour, and the requirements of software systems. Such methods are provided by the *Unified Modelling Language* (UML) and its *Object Constraint Language* (OCL) as notations (as diagrams) for describing complex *object-oriented* software systems, where the parts of these systems during execution are called *objects*. Objects react to *messages* they exchange among each other and with their *environment*, that is, with their external world. This exchange of messages is considered to be (part of) their *behaviour*.

UML provides the schema language of *class diagrams* for describing the structure, that is, the parts of the system and which parts may communicate with each other, and the notation of *state machines* for describing the behaviour of a system or its parts. OCL is used to describe the *requirements* on the system. Requirements are the properties a system has to satisfy and describe its *correct* functioning from the point of view of these given requirements.

In order to enable the development and the formal validation of these systems we have to define a *formal semantics* for the notations of UML and OCL. This means, we assign a precise meaning to the constructs of UML and OCL. This is necessary, because at present UML notations have no precise meaning. To this end, we define an unambiguous subset of UML class diagrams and define a precise mathematical semantics for this subset in Chapter 2.

UML and OCL are *typed languages*. This means that there are so-called *typing rules* on diagrams and expressions which describe when they are well-formed and therefore

Summary

have a meaning that makes sense. In Chapter 3 we show that these rules are too inflexible for writing requirements while the system is still under development. Namely, development causes changes in the system which, according to the typing rules, unexpectedly render requirements ill-formed. As a consequence, these requirements are considered nonsensical in UML. However, in our semantics they have a well-defined meaning, which has not been changed by the development step. To overcome this problem we propose extensions of the typing rules (based on so-called intersection types, union types, and bounded operator abstraction) which also improve the integration of the OCL into the UML, and which considers more requirements as well-formed.

We use *logic* to formalise the meaning of UML diagrams and OCL expressions in order to enable their formal validation. Logic makes the use of *interactive theorem provers* possible. Theorem provers assist in constructing proofs of the correct functioning of systems. This means that a system and its requirements have to be *translated* into logic. The result of this translation should be of a form that allows one to exploit all automated reasoning facilities offered by the theorem prover in finding a proof, because otherwise the construction of proofs quickly becomes complex, burdensome, and (economically) infeasible. In Chapter 4 we describe such a translation, performed by a computer program, into the input language of the theorem prover PVS and show why the translator preserves the meaning of the system and its requirements.

In order to support the specification of systems during early stages of design, we have analysed the semantics of OCL Message Expressions in Chapter 5. Message expressions specify whether messages have been sent by objects. These have been found to be inadequate. Therefore, we propose introducing *history variables* to OCL. History variables allow not only to specify and reason about the messages sent during the invocation of an operation, but also about the history of *all* messages sent and received by an object. We also show that everything which can be expressed by message expressions can also be expressed with history variables.

We strictly separate local specifications, which are requirements on the internal state of objects (and play the role of so-called *data invariants*), from local behavioural specifications, which describe the messages sent and received by an object. At a third level, we introduce global specifications which specify how objects in a system may interact.

This formalisation leads to a compositional history-based specification formalism, for which we give a compositional proof rule in Chapter 6. A specification is called *compositional* if the function of a system can be derived from the functions of its parts and the way they are put together. The main problem to solve here is the treatment of the evolution of object structures. Object structures change because objects learn about other objects during their lifetime, which enables them to communicate with new acquaintances; especially, when objects create new objects.

Finally, in Chapter 7 we extend this history-based formalism to real-time specifications. We specify a part of a *medium altitude reconnaissance system*, which is deployed by the Royal Dutch Air-Force, and prove its correctness. This example shows that the methods described in this thesis can be applied in principle to real-world case studies.

Samenvatting

Ingebedde real-time systemen zijn (kleine) computer systemen die ertoe dienen de apparaten waarin ze ingebed zijn te helpen (be)sturen. Voorbeelden van zulke apparaten zijn DVD spelers, automatische remmen, autopiloten, mobiele telefoons en Magnetic-Resonance scanners. Zulke ingebedde systemen komen meer en meer voor en worden in hoog tempo snel complexer. Ook komt het steeds vaker voor dat mensenlevens van het correct functioneren van de door hen gestuurde apparaten afhangen. Deze ontwikkeling is niet meer te stuiten. Daarom is het belangrijk dat zulke apparaten correct functioneren. En dat hangt weer af van het correcte functioneren van de hen sturende real-time systemen.

Aangezien deze systemen alom tegenwoordig zijn, zijn er industriële standaards ontwikkeld om hun functionaliteit te beschrijven. Een veel gebruikte standaard hiervoor is de UML (voor Unified Modeling Language—de naam zegt het al) en in het bijzonder zijn de taal OCL (voor Object Constraint Language), die ertoe dient de bedoelde betekenis van constructies in UML nader vast te leggen.

Jammer genoeg is noch de betekenis van UML, noch die van OCL eenduidig vastgelegd. (Sommige bronnen beweren dat dit met opzet gebeurd is om tegenstrijdige industriële belangen te dienen). Het is duidelijk dat als je niet precies weet wat een bepaalde taalkonstruktie betekent, je hem ook niet met 100 % zekerheid kunt gebruiken om een apparaat te sturen waar mensenlevens van afhangen.

Om in deze situatie verandering te brengen is dit proefschrift geschreven.

Het beschrijft een formele, dat wil zeggen, in wiskundige zin exacte, semantiek voor de taalconstructies van UML en OCL, en voorziet deze talen van een zinvol typesysteem dat ertoe dient om aan te geven in welke context een UML of OCL taalkonstruktie zinvol te gebruiken is. Dit type systeem is, als onderdeel van dit proefschrift, geïmplementeerd, zodat het voldoen aan de betreffende typeringsregels elektronisch kan worden gecheckt.

Om te bewijzen dat deze semantiek eenduidig is, is hij omgezet in de specificatietaal van PVS, een elektronisch systeem dat bewijzen van wiskundige stellingen op hun correctheid checkt en dat veel gebruikt wordt om er correctheidsbewijzen van programma's elektronisch mee te controleren.

Vervolgens worden in dit proefschrift een paar karakteristieke toepassingen van UML korrekst bewezen, waarbij de gebruikte semantiek die is welke in dit proefschrift vastgelegd wordt, de architectuur van deze toepassingen in UML gegeven wordt en hun functionaliteit in OCL wordt gespecificeerd.

Samenvatting

De eerste toepassing betreft een programma voor de Zeef van Eratosthenes, dat ertoe dient de priemgetallen te genereren. Dit ontleent zijn belang aan het feit dat de desbetreffende “zeef” zich in principe een onbegrensd aantal malen (recursief) oproepen kan. Er wordt aangegeven hoe dit probleem in PVS gecodeerd kan worden, waarna de correctheid van dit programma met behulp van PVS bewezen wordt.

De tweede toepassing is ontleend aan een programma dat gebruikt wordt door de Koninklijke Luchtmacht in hun verkenningsvliegtuigen om daar zeer nauwkeurige fotos mee te maken. Wanneer namelijk vanuit straaljagers gefotografeerd wordt, moet voor nauwkeurige fotos een compensatie-mechanisme ingebouwd worden in verband met de tijdens een opname afgelegde afstand; die moet door bewegende spiegels gecompenseerd worden. Van het centrale deel van het elektronische ingebedde real-time systeem dat de beweging van deze spiegels regelt wordt een nauwkeurige specificatie in OCL gegeven en met behulp van PVS bewezen dat de UML beschrijving van de architectuur van het desbetreffende besturingssysteem aan deze specificatie voldoet.

Daarmee wordt aangetoond dat deze semantieken en hun omzetting in PVS zich er in principe toe lenen om er industriële toepassingen, waarvan architectuur en functionaliteit in UML en OCL beschreven zijn, mee korrekt te bewijzen.

Curriculum Vitæ

January 30, 1975 Born in Pinneberg, Germany.

August 1981–July 1985 Hans-Clausen-Schule, Pinneberg.

August 1985–June 1994 Diploma qualifying for university admission (Abitur) from *Johannes-Brahms-Schule*, Pinneberg, (major fields of study: mathematics and chemistry).

July 1994–September 1995 Alternative civilian service at the nursing home Haus am Rosengarten, Pinneberg.

October 1995–November 2000 Diploma from Christian-Albrechts-Universität zu Kiel (CAU) in computer science under supervision of Yassine Lakhnech and Willem-Paul de Roever. Title of diploma thesis: “Verifikation parameterisierter Netzwerke durch Abstraktion (Verification of parameterised networks by abstraction)”. Minor subject: electrical engineering.

January 1997–March 1999 Student assistant (Wissenschaftliche Hilfskraft) at CAU, Institute of Economics (Operations Research), implementing a distributed version of a resource constraint scheduling problem.

April 1999–December 2000 Student assistant at CAU, Institute of Computer Science and Applied Mathematics (Software Technology), implementing static analysers for sequential function charts.

October 2000–December 2001 Assistant professor (nebenamtlicher Dozent) lecturing on *Algorithms and data structures* at FH Nordakademie.

January 2001–today Researcher at Christian-Albrechts-Universität zu Kiel, working for the IST-project *Omega* (IST-2001-33522), DFG/NWO-project *Mobi-J* (RO-1122/9-1 and RO1122/9-2), and DFG-project *SFC-Check* (LA-1021/6-1).

Current address: Christian-Albrechts-Universität zu Kiel
Institut für Informatik und Praktische Mathematik
24098 Kiel
Germany

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