

## Advancing diffusion MRI: improving image quality and getting rid of the fat

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# Chapter 3

### SENSE-based multipeak water/fat separation for diffusion-weighted imaging using self-navigated interleaved EPI

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#### **Synopsis**

The presence of fat signals is one challenge for diffusion-weighted EPI, especially when considering the multi-peak spectrum nature of fat. In this work, we propose an improved SENSE-based water/fat separation algorithm to suppress multi-peak fat signals and apply this specifically to diffusion-weighted multi-shot EPI. The motion-induced shot-to-shot phase variations, an inevitable challenge in multi-shot DWI, are incorporated into the signal model using either a self-navigation or an extra-navigated method. The results show that the proposed SENSE-based algorithm yields good water/fat separation for non-diffusion and diffusion data with a multi-peak fat spectrum model.

#### 3.1 Introduction

Multi-shot interleaved EPI (msh-EPI) provides significant improvement for diffusion-weighted imaging (DWI) to allow images with higher spatial resolution and less geometric distortions<sup>1</sup>. However, multi-shot acquisitions for DWI applications are susceptible to physiological motion-induced phase variations between the shots. This difficulty is usually addressed by 1) acquiring additional navigator images<sup>1,2</sup>, or 2) employing self-navigation approaches<sup>3,4</sup>. Moreover, residual fat artefacts represent another difficulty in DWI due to large water-fat shift in phase-encoding direction. Fat suppression<sup>5</sup> techniques widely used for eliminating fat, often fail for large B<sub>0</sub> inhomogeneities. Moreover, they do not fully take into account the multipeak nature of the fat spectrum (e.g., Olefinic peak, 0.61 ppm to water). Recently, chemical-shift encoding has been proposed to jointly separate water and fat images while estimating the B<sub>0</sub> inhomogeneities<sup>6-8</sup>. Nevertheless, the need to acquire images at multiple TEs may limit its efficiency in clinical applications. Alternatively, Uecker et al. has proposed an approach exploiting the chemical-shift-induced spatial shift of fat using sensitivity encoding (SENSE) to disentangle water and fat signals. The method is validated with a single-peak fat spectra and single-shot EPI images.

In this work, we propose to include the multipeak nature of the fat spectrum into the approach by Uecker et al.<sup>9</sup> to separate water and fat in EPI based on SENSE. This approach is extended to multi-shot, in-vivo DWI using a novel water-fat phase self-navigation method to compensate for motion-induced phase errors, making the need for measuring an extranavigator echo obsolete.

#### 3.2 Method

The forward model of the DW msh-EPI data at a certain b-value can be written as:

$$s = \sum_{n}^{N} Q_{n}(\hat{F}\hat{C}\widehat{\Phi}_{w,n}\rho_{w} + \alpha_{m} \sum_{m}^{M} \widehat{\Phi}_{f,m}\widehat{F}\hat{C}\widehat{\Psi}_{f,n}\rho_{f})$$

$$\tag{1}$$

where  $\hat{F}$  is the Fourier transform operator,  $\hat{\mathcal{C}}$  the SENSE operator,  $\widehat{\Phi}_{w,n}$  and  $\widehat{\Phi}_{f,n}$  the operators of motion-induced phase errors for water and fat, respectively.  $\alpha_m$  is the relative amplitude weight,  $\widehat{\Psi}_{f,m}$  denotes the fat off-resonance operator for peak m, and  $Q_n$  represents the k-space trajectory for each shot n. s and  $\rho_w/\rho_f$  are the vectorized representations of the measured multi-shot k-space signal and the target water/fat images. The water/fat images can be calculated by minimizing:

$$\{\rho_w, \rho_f\} = \underset{\rho_w, \rho_f \in \mathbb{C}}{\operatorname{argmin}} \|\hat{A}X - s\|_2^2$$
 (2)

where  $X = [\rho_w, \rho_f]^T$  and  $\hat{A}$  is the coefficient matrix, containing all the operators described above. For multi-shot acquisition, the relatively small spatial shift of fat compared to single-shot EPI makes the accuracy of coil-sensitivity maps (CSM) particularly important. Therefore, the advanced JSENSE described in Shin et al. 10 is used to self-calibrate the CSM for b=0 s/mm². Two threshold water/fat masks can be calculated using the separated  $\rho_w$  and  $\rho_f$  images to mask the CSM and stabilize the phase estimation step.

For the diffusion-weighted cases, the SENSE-based water/fat separation is performed for each shot data to calculate motion-induced phase errors for water/fat individually. Inspired by  $MUSE^3$ , the water/fat-adapted SENSE formalism is used to recover ghost-free images for each shot n. First, this can be done by solving the equation:

$$s_n = Q_n(\hat{F}\hat{C}\rho_{w,n} + \alpha_m \sum_{m}^{M} \widehat{\Psi}_{f,m} \hat{F}\hat{C}\rho_{f,n})$$
(3)

using conjugate gradient (CG), to estimate  $\rho_{w,n}$  and  $\rho_{f,n}$  for each individual shot n from the measured data  $s_n$ . Then, the motion-induced phase  $\phi_{w,n}$  and  $\phi_{f,n}$  can be calculated separately for water and fat by:

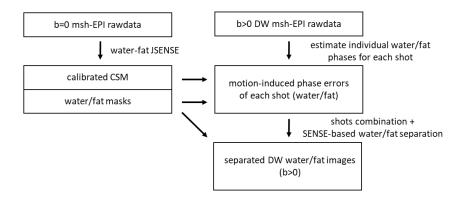
$$e^{i\phi_{W/f,n}} = \frac{\rho_{W/f,n}}{|\rho_{W/f,n}|}. (4)$$

In addition, k-space triangular window<sup>11</sup> is applied individually on  $e^{i\phi_{w,n}}/e^{i\phi_{f,n}}$  to enforce smoothness and construct the operators  $\widehat{\Phi}_{w,n}/\widehat{\Phi}_{w,n}$  in Eq.1. The window width is chosen to be half of the matrix size. The whole pipeline is illustrated in figure 1.

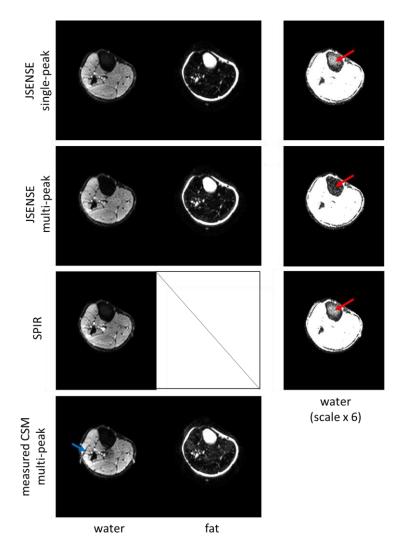
DW msh-EPI spin-echo data of the lower leg of a normal volunteer was acquired using a 3T-MRI (Philips Healthcare, Best, Netherlands) with the following parameters: TR/TE=2000/60ms, resolution 1.5×1.5×4 mm³, three b-values (0, 300, 600 s/mm²), 3 shots, an 8-channel knee coil. For comparison, an extra-navigator² was acquired for each shot. In addition, another fat suppressed DWI scan was acquired using SPIR⁵ and reconstructed through IRIS algorithm².

#### 3.3 Results and Discussion

Figure 2 shows the non-diffusion dataset comparing the JSENSE-calibrated CSM with single-peak/multi-peak<sup>8</sup> fat model and the SPIR scan. The result for a conventional pre-scan CSM with a multi-peak fat model is shown for comparison. The JSENSE results show improved water images compared to the pre-scan for both spectral fat models. This is mainly due to the geometric distortion mismatch between the EPI images and the reference scan. Besides, the water images with adjusted level/window show the capability of the algorithm to deal with the multi-peak fat spectrum, which is superior to fat-suppression by SPIR. Figure 3 shows water images with different b-values and the associated ADC maps for (1) SPIR, (2) the SENSE-based water/fat separation with extra-navigators and (3) with self-navigation. SPIR shows an unsuppressed fat rim, probably arising from strong B<sub>1</sub><sup>+</sup> inhomogeneities. Some artefacts can be seen in the SENSE-based water image with extra-navigators, which are not present for the self-navigated results. Figure 4 shows the estimated water/fat phases derived for self-navigation.

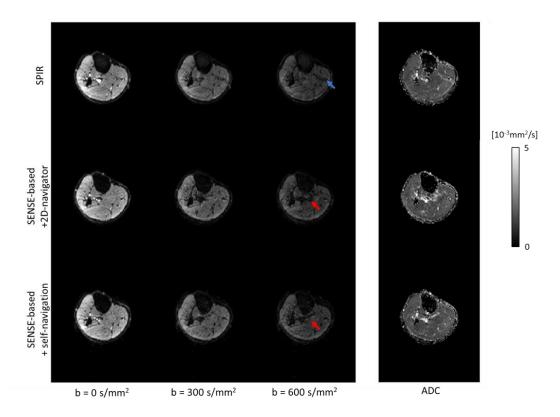


**Figure 1.** Pipeline of the reconstruction. Self-calibrated coil-sensitivity maps (CSM) can be acquired by performing water-fat JSENSE<sup>10</sup> on non-diffusion msh-EPI data. Two separated water/fat masks can be calculated at the same time to mask the CSM for water/fat channels individually. Then, the calibrated CSM will be used to estimate water/fat phase maps for each individual shot. Finally, the DW water/fat images can be obtained by performing SENSE-based water/fat separation after shots combination.

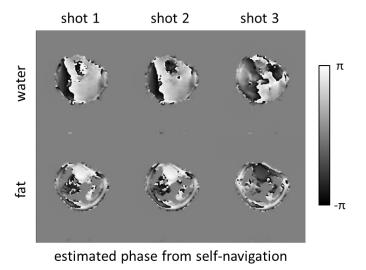


**Figure 2.** Comparison of different reconstructions for the non-diffusion 3-shot data. First three rows show separated water/fat results using single-peak and multi-peak fat model, and a SPIR image. In the

level/window adjusted water images, the signals of olefinic peak are suppressed in the multi-peak result, while still survive in the water images with single-peak fat model and SPIR (red arrows). Last row shows water/fat image using CSM acquired by a pre-scan. Some artefacts appeared in the water image (blue arrow), which can be mitigated by using self-calibration (JSENSE).



**Figure 3.** Comparison of the three fat suppression methods for a 3-shot DW msh-EPI scan. Some artefacts can be seen in the SPIR results mainly due to  $B_1^+$  inhomogeneities (blue arrow). Signal dropouts can be seen for the SENSE-based separation using an extra 2D-navigator, which can be mitigated using self-navigation (red arrows). The effects of all the above described artefacts can also be seen in the final ADC maps for each method.



**Figure 4.** Estimated phase maps of the three shots DW data (b=600 s/mm<sup>2</sup>). Separated water/fat phases are obtained by treating each shot dataset of the DW msh-EPI as an individual water/fat

SENSE problem. The proposed self-navigation algorithm can estimate the water/fat phase maps for each shot and provide effective water/fat separation shown in figure 3.

#### 3.4 Conclusion

The proposed method allows for an efficient SENSE-based water/fat separation of non-DW and DW msh-EPI data. The SENSE-based solution requires only one acquisition for each b-value to separate water/fat with a multi-peak fat model. This directly increase the flexibility and is important when different b-values/diffusion directions are desired. Future studies will include undersampling for acceleration and use of phased array coils with more channels to support higher segmentation factors.

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