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Learning class-imbalanced problems from the perspective of data intrinsic characteristics

Kong, J.

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Appendices

APPENDIX A

Additional Experimental Results

Table A.1: Performance results of decision tree (C5.0) on the dataset *Contraceptive*. “1 0 1 0” represents “safe(1) borderline(0) rare(1) outlier(0)”, i.e. only safe and rare samples are oversampled. $R_{min/all}$ and TS indicate the different rules for identifying types of samples.

Combination	MinAcc		MAUC	
	$R_{min/all}$	TS	$R_{min/all}$	TS
1 1 1 1	0.4154	0.4154	0.6736	0.6744
1 1 1 0	0.3925	0.3503	0.6734	0.6735
1 1 0 1	0.3800	0.3846	0.6714	0.6753
1 0 1 1	0.3978	0.3690	0.6607	0.6617
0 1 1 1	0.3530	0.3695	0.6670	0.6643
1 1 0 0	0.4296	0.4360	0.6807	0.6834
1 0 1 0	0.3773	0.3518	0.6689	0.6655
0 1 1 0	0.3865	0.3882	0.6737	0.6699
1 0 0 1	0.3814	0.3932	0.6669	0.6700
0 1 0 1	0.3988	0.3950	0.6725	0.6678
0 0 1 1	0.3963	0.3605	0.6679	0.6626
1 0 0 0	0.4457	0.4360	0.6884	0.6826
0 0 1 0	0.3666	0.3688	0.6698	0.6676
0 1 0 0	0.3899	0.4207	0.6771	0.6768
0 0 0 1	0.4343	0.4040	0.6841	0.6622

Table A.2: Performance results of decision tree (C5.0) on the dataset *Thyroid*. “1 0 1 0” represents “safe(1) borderline(0) rare(1) outlier(0)”, i.e. only safe and rare samples are oversampled. $R_{min/all}$ and TS indicate the different rules for identifying types of samples. “–” means that there are not enough samples to execute the k -nearest-neighbor algorithm in the oversampling step.

Combination	MinAcc		MAUC	
	$R_{min/all}$	TS	$R_{min/all}$	TS
1 1 1 1	0.8648	0.8648	0.9813	0.9808
1 1 1 0	0.7789	0.7708	0.9829	0.9733
1 1 0 1	0.7221	0.7486	0.9726	0.9736
1 0 1 1	0.7227	0.7440	0.9703	0.9737
0 1 1 1	0.9432	0.9350	0.9831	0.9830
1 1 0 0	0.7011	–	0.9774	0.9712
1 0 1 0	–	0.7306	–	0.9765
0 1 1 0	0.7694	0.7756	0.9838	0.9815
1 0 0 1	0.7816	–	0.9735	0.9744
0 1 0 1	0.8224	–	0.9831	0.9814
0 0 1 1	–	–	–	–
1 0 0 0	–	–	–	–
0 0 1 0	–	–	–	–
0 1 0 0	–	–	–	–
0 0 0 1	–	–	–	–

Table A.3: Performance results of decision tree (C5.0) on the dataset *Wine*. “1 0 1 0” represents “safe(1) borderline(0) rare(1) outlier(0)”, i.e. only safe and rare samples are oversampled. $R_{min/all}$ and TS indicate the different rules for identifying types of samples. “–” means that there are not enough samples to execute the k -nearest-neighbor algorithm in the oversampling step.

Combination	MinAcc		MAUC	
	$R_{min/all}$	TS	$R_{min/all}$	TS
1 1 1 1	0.9385	0.9297	0.9493	0.9495
1 1 1 0	0.9578	0.9600	0.9619	0.9606
1 1 0 1	0.9232	0.9192	0.9577	0.9560
1 0 1 1	0.9500	0.9800	0.9546	0.9553
0 1 1 1	–	–	–	–
1 1 0 0	0.9068	0.9436	0.9583	0.9556
1 0 1 0	0.8986	0.9378	0.9531	0.9547
0 1 1 0	–	–	–	–
1 0 0 1	0.9618	0.9374	0.9529	0.9492
0 1 0 1	–	–	–	–
0 0 1 1	–	–	–	–
1 0 0 0	0.9532	0.9636	0.9530	0.9475
0 0 1 0	–	–	–	–
0 1 0 0	–	–	–	–
0 0 0 1	–	–	–	–

Table A.4: Performance results of decision tree (C5.0) on the dataset *Glass*. “1 0 1 0” represents “safe(1) borderline(0) rare(1) outlier(0)”, i.e. only safe and rare samples are oversampled. $R_{min/all}$ and TS indicate the different rules for identifying types of samples. “–” means that there are not enough samples to execute the k -nearest-neighbor algorithm in the oversampling step.

Combination	MinAcc		MAUC	
	$R_{min/all}$	TS	$R_{min/all}$	TS
1 1 1 1	0.6243	0.6291	0.8603	0.8605
1 1 1 0	0.7357	0.6778	0.8903	0.8958
1 1 0 1	0.4933	0.7111	0.9010	0.8925
1 0 1 1	0.4778	0.6156	0.8798	0.8840
0 1 1 1	0.5211	0.6522	0.8954	0.8952
1 1 0 0	–	–	–	–
1 0 1 0	–	–	–	–
0 1 1 0	–	–	–	–
1 0 0 1	–	–	–	–
0 1 0 1	–	–	–	–
0 0 1 1	–	–	–	–
1 0 0 0	–	–	–	–
0 0 1 0	–	–	–	–
0 1 0 0	–	–	–	–
0 0 0 1	–	–	–	–

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