

 $\begin{tabular}{ll} \textbf{Model-assisted robust optimization for continuous black-box problems} \\ \textbf{Ullah, S.} \end{tabular}$ 

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## Propositions accompanying the thesis

## Model-Assisted Robust Optimization for Continuous Black-Box Problems

## Sibghat Ullah

- 1. Kriging, polynomials, and support-vector machines are excellent modeling techniques in the context of robust optimization. *Chapter 3*.
- 2. PCA and Autoencoders provide low-dimensional representations that can be used to efficiently solve high-dimensional numerical optimization problems. *Chapter 3*.
- 3. Moment-generating function of the improvement and expected improvement criterion prove to be excellent choices for robust Bayesian optimization, especially when dealing with high dimensionality. *Chapter 4*.
- 4. Mini-max robustness is the most efficient robustness criterion in terms of fixed budget and fixed target analyses. *Chapter 5*.
- 5. In numerical optimization problems, there can be multiple types of uncertainties present, particularly in the objectives and the constraints. As a result, the user needs to determine which type and structure of uncertainty to focus on, based on its potential impact.
- 6. Surrogate-assisted optimization provides an efficient mechanism to solve problems with uncertainty and noise in the search variables. This kind of uncertainty can be represented in a deterministic or a probabilistic fashion.
- 7. The notion of robustness can also be applied to areas such as machine learning and pattern recognition, particularly when dealing with uncertain data.
- 8. The scientific community requires a test suite for robust optimization problems to effectively validate and compare research findings in this field.
- 9. While practicing robust optimization in real-world situations, the hardest thing to achieve is the balance between performance and stability.