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Dormancy in stochastic interacting systems

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Appendix of Part II

Appendix: Chapter 5

Inverse of the boundary-layer matrix

The inverse of the matrix M_ϵ defined in (5.115) is given by (α_1 and α_2 are as in (5.116))

$$M_\epsilon^{-1} := \frac{1}{Z} \begin{bmatrix} -m_{13} & -m_{14} & m_{13} & m_{14} \\ m_{21} & m_{22} & m_{23} & m_{24} \\ m_{31}(\alpha_2) & m_{32}(\alpha_2) & m_{33}(\alpha_2) & m_{34}(\alpha_2) \\ -m_{31}(\alpha_1) & -m_{32}(\alpha_1) & -m_{33}(\alpha_1) & -m_{34}(\alpha_1) \end{bmatrix}, \quad (\text{C.1})$$

where

$$\begin{aligned} Z &:= \alpha_1^{N+1} [\alpha_2(1-\epsilon)(\alpha_2^{N-1}+1) + 2\epsilon(\alpha_2^{N+1}+1)] \\ &\quad \times [\alpha_2(1+N)(1-\epsilon)(\alpha_2^{N-1}-1) + 2\epsilon(N+\epsilon)(\alpha_2^{1+N}-1)], \\ m_{13} &:= \alpha_1^{N+1} [\alpha_2(1-\epsilon)(\alpha_2^{N-1}+1) + 2\epsilon(\alpha_2^{N+1}+1)] \\ &\quad \times [\alpha_2(1-\epsilon)(\alpha_2^{N-1}-1) + \epsilon(\alpha_2^{N+1}-1)], \\ m_{14} &:= \epsilon \alpha_1^{N+1} [\alpha_2(1-\epsilon)(\alpha_2^{N-1}+1) + 2\epsilon(\alpha_2^{N+1}+1)] (\alpha_2^{N+1}-1), \\ m_{21} &:= (1+N)(1-\epsilon)^2 (\alpha_2^{N-1} - \alpha_1^{N-1}) - \epsilon(1-\epsilon)^2 (\alpha_2 - \alpha_1) \\ &\quad + \epsilon^2(1+2N+\epsilon)(\alpha_2^{N+1} - \alpha_1^{N+1}) + \epsilon(1-\epsilon)(2+3N+\epsilon)(\alpha_2^N - \alpha_1^N), \\ m_{22} &:= \epsilon [(1-\epsilon)(1+N)(\alpha_2^N - \alpha_1^N) + \epsilon(1+2N+\epsilon)(\alpha_2^{N+1} - \alpha_1^{N+1})], \\ m_{23} &:= \epsilon(1-\epsilon)[(N+\epsilon)(\alpha_2 - \alpha_1) - (1-\epsilon)(\alpha_2^N - \alpha_1^N) - \epsilon(\alpha_2^{N+1} - \alpha_1^{N+1})], \\ m_{24} &:= -\epsilon(1-\epsilon)[(1+N)(\alpha_2 - \alpha_1) + \epsilon(\alpha_2^{N+1} - \alpha_1^{N+1})], \end{aligned} \quad (\text{C.2})$$

and the polynomials $m_{31}(z), m_{32}(z), m_{33}(z), m_{34}(z)$ are defined as

$$\begin{aligned} m_{31}(z) &:= -(1-\epsilon)^2 z - \epsilon(1-\epsilon) + (1-\epsilon)(N+\epsilon)z^N - \epsilon(1-2N-3\epsilon)z^{N+1}, \\ m_{32}(z) &:= -(1-\epsilon)(1+N)z^N - \epsilon(1-\epsilon) - \epsilon(1+2N+\epsilon)z^{N+1}, \\ m_{33}(z) &:= (1-\epsilon)^2 z^N + \epsilon(1-\epsilon)z^{N+1} - (1-\epsilon)(N+\epsilon)z + \epsilon(1-2N-3\epsilon), \\ m_{34}(z) &:= (1+N)(1-\epsilon)z + \epsilon(1-\epsilon)z^{N+1} + \epsilon(1+2N+\epsilon). \end{aligned} \quad (\text{C.3})$$

We remark that most of the terms appearing in the inverse simplify because of (5.117). We define the four vectors $\vec{c}_1, \vec{c}_2, \vec{c}_3, \vec{c}_4$ as the respective rows of M_ϵ^{-1} , i.e.,

$$\begin{aligned} \vec{c}_1 &:= (M_\epsilon^{-1})^T \vec{e}_1, & \vec{c}_2 &:= (M_\epsilon^{-1})^T \vec{e}_2, \\ \vec{c}_3 &:= (M_\epsilon^{-1})^T \vec{e}_3, & \vec{c}_4 &:= (M_\epsilon^{-1})^T \vec{e}_4, \end{aligned} \quad (\text{C.4})$$

where

$$\begin{aligned}\vec{e}_1 &:= [1 \ 0 \ 0 \ 0]^T, & \vec{e}_2 &:= [0 \ 1 \ 0 \ 0]^T, \\ \vec{e}_3 &:= [0 \ 0 \ 1 \ 0]^T, & \vec{e}_4 &:= [0 \ 0 \ 0 \ 1]^T.\end{aligned}$$

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