



Cause-effect analysis for sustainable development policy

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1 **Cause-effect analysis for sustainable development policy**

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7 **Abstract**

8 The sustainable development goals (SDGs) launched by the United Nations (UN) set a new direction for
9 development covering the environmental, economic and social pillars. Given the complex and
10 interdependent nature of the socio-economic and environmental systems, however, understanding the
11 cause-effect relationships between policy actions and their outcomes on SDGs remains as a challenge. We
12 provide a systematic review of cause-effect analysis literature in the context of quantitative sustainability
13 assessment. The cause-effect analysis literature in both social and natural sciences has significantly
14 gained its breadth and depth, and some of the pioneering applications have begun to address sustainability
15 challenges. We focus on randomized experiment studies, natural experiments, observational studies, and
16 time-series methods, and the applicability of these approaches to quantitative sustainability assessment
17 with respect to the plausibility of the assumptions, limitations and the data requirements. Despite the
18 promising developments, however, we find that quantifying the sustainability consequences of a policy
19 action, and providing unequivocal policy recommendations is still a challenge. We recognize some of the
20 key data requirements and assumptions necessary to design formal experiments as the bottleneck for
21 conducting scientifically defensible cause-effect analysis in the context of quantitative sustainability
22 assessment. Our study calls for the need of multi-disciplinary effort to develop an operational framework
23 for quantifying the sustainability consequences of policy actions. In the meantime, continued efforts need
24 to be made to advance other modeling platforms such as mechanistic models and simulation tools. We
25 highlighted the importance of understanding and properly communicating the uncertainties associated
26 with such models, regular monitoring and feedback on the consequences of policy actions to the modelers
27 and decision-makers, and the use of what-if scenarios in the absence of well-formulated cause-effect
28 analysis.

29 **Keywords**

30 Sustainable development goals; causality; cause-effect mechanisms; quantitative sustainability

31 assessment; sustainability policy

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32 **1 Introduction**

33 The Sustainable Development Goals (SDGs, hereafter) launched on January 1, 2016 include 17 goals, 169
34 targets and 303 indicators (United Nations 2014, Malik et al. 2015), which will help frame the agendas
35 and policies of the United Nations' member states through 2030 (Hák et al. 2016). These goals are not
36 only comprehensive, covering the economic, social and environmental dimensions of sustainability, but
37 also highly interconnected (International Council for Science 2015), making it essential to understand
38 synergies, trade-offs and conflicts between them in order to support decisions (Schindler and Hilborn
39 2015). Without such understanding, a policy to improve on one goal could conflict with another goal. For
40 example, policies targeting at improving energy provision could conflict with another goal on climate-
41 change mitigation, or those aiming at the protection of marine ecosystem could clash with the provision
42 of sustainable food for all (Laurenti and Sinha 2015).

43 Various tools and metrics have supported sustainable development decisions, which we collectively refer
44 to quantitative sustainability assessments (QSAs) in this review. Examples of QSAs include, but not
45 limited to, life cycle assessment (LCA) (Guinée 2002, ISO 2006, Hellweg and Mila i Canals 2014),
46 various footprinting approaches (Wiedmann and Minx 2007, Peters 2010, Hoekstra and Mekonnen 2012,
47 Mancini et al. 2015, Michalsky and Hooda 2015), assessment of planetary boundaries (Rockström et al.
48 2009, Hughes et al. 2013, Whiteman et al. 2013, Steffen and Richardson 2015), environmental input-
49 output models (Huppes et al. 2006, Tukker et al. 2006, Suh 2009, Hertwich 2010, Lenzen et al. 2012,
50 Hertwich et al. 2014), ecosystem valuation approaches (Groot et al. 2010, Costanza et al. 2014), and
51 material flow analysis (MFA) (Matthews et al. 2000, Brunner and Rechberger 2004, Haberl et al. 2007,
52 Fischer-Kowalski and Swilling 2011), among others [see e.g. (Ness et al. 2007)]. In particular, so called,
53 consequential LCA (CLCA) aims at quantifying the consequences that a certain action or a policy
54 decision has on the environment and natural resources (Brander et al. 2008, Creutzig et al. 2012, Zamagni
55 et al. 2012, Plevin and Delucchi 2014, Suh and Yang 2014).

56 The complexity and the interconnected nature of the socio-economic and environmental systems,
57 however, poses a challenge to QSA practitioners in modeling the consequences of a policy action in the
58 context of sustainable development (Cucurachi and Suh 2015). Furthermore, recent developments in
59 economics, ecosystem science, and systems biology on causality research have yet to be embraced by
60 QSA approaches.¹ Over the past decades, the causality literature has evolved to address various
61 conceptual and technical issues such as endogeneity (Antonakis et al. 2014, Kreuzer 2016) and reverse
62 causality [see e.g. (Mei-chu 1987, Chong and Calderon 2000, Barsky and Kilian 2004, Chaumont et al.
63 2012)] in parsing out causal relationships from complex phenomena. For example, Angrist and Krueger
64 (1992) test the effect of children's age when starting school on their eventual years of schooling
65 completed and on educational attainment. Using instrumental variables, the authors conclude that the
66 effect of the starting age on educational attainment is modest. Instrumental variables have also been used
67 to test the effects of education on health (Cutler et al. 2008, Grossman 2008, Conti et al. 2010, Cutler and
68 Lleras-Muney 2010, Heckman et al. 2014), education on well-being (Oreopoulos and Salvanes 2011,
69 Oreopoulos and Petronijevic 2013), and social connections on well-being (Kahneman and Krueger 2006,
70 Fowler et al. 2008). However, few of such techniques have been applied to QSAs.

71 This review aims at surveying the techniques of cause-effect analysis in the context of QSAs. For each
72 method to infer causality (cause-effect analysis technique in the remainder of the text), we present and
73 review relevant applications in the field of sustainability that show how cause-effect analysis techniques
74 can allow QSAs to increase the value of information they provide to decision makers. Our survey of

¹ For example, Weinzettel et al. (2013) use multi-linear regression and concluded that affluence drives the global displacement of land use, thus being the main cause of biodiversity loss globally. The study does provide a strong correlation between affluence and biodiversity loss but does not univocally allow interpretation of the results as a causal relationship. Likewise, Suweis et al. (2013, 2015) use a stochastic logistic model to assess whether the population growth of a nation is driven (i.e. caused) by either local availability of water resources used or by import of water resources from neighboring countries. As acknowledged by the authors, both studies do not consider a number of "other environmental, cultural, and health-related factors", thus limiting the interpretability of the result as a causal relationship. Some of these problems have been widely discussed and well understood in the causality literature (Aldrich, 1995; Rimer, 1998; Simon and Iwasaki, 1988).

75 causality literature was drawn from peer-reviewed articles on theory and methods, causality handbooks,
76 and case studies applying the techniques. Based on the literature surveyed, we classify the analytical
77 approaches to cause-effect analysis techniques. Each class of techniques was, in turn, searched on the ISI
78 Web of Science and on Google Scholar in combination with the keywords ‘sustain*’, ‘environ*’,
79 ‘emissions’, ‘pollut*’, ‘econ*’, ‘CO2’, and ‘GDP’.

80 The remainder of the review is organized as follows: the next section presents a short chronology of
81 causality theory; in section 3, we start from the ideal approach to causality provided by Rubin’s causal
82 model, and then we analyze the techniques that are based on observational (i.e. non-experimental) data; in
83 section 4 we discuss the applicability of cause-effect analysis techniques to QSA; finally section 5
84 discusses outlook to close this review.

85 **2 A brief chronology**

86 Causality has interested philosophers and scientists since the time of Aristotle (see *Physics II 3 and*
87 *Metaphysics V 2*). For millennia, however, causal problems have often rested in the realm of
88 philosophical delight rather than inspiring scientific research.

89 Pearl (2000a) notes that the questions on causality did not enter into formal scientific discourses for a
90 good part of the 19th century. In the dawn of the 20th century, Hume (1902 sec. VII) formally defined a
91 cause as “an object followed by another, and where all the objects, similar to the first, are followed by
92 objects similar to the second. Or, specifically, where, if the first object had not been, the second never had
93 existed”. A similar idea of cause was also at the basis of the experimental work of Mill (1856). However,
94 Russel (1912) stated that causal relationships and physical equations are incompatible, describing
95 causality as “a word relic” and excluding the existence of causality from mathematics and physics. In
96 1911, Pearson still described causality as “another fetish amidst the inscrutable arcana of even modern
97 science” (Pearson 1911). Interestingly, a mechanistic view of causality also existed in the early 20th
98 century philosophy. For example, Laplace thought that cause and effect can be understood perfectly given
99 enough knowledge and data: “We may regard the present state of the universe as the effect of the past and

100 the cause of the future. An intellect which at any given moment knew all of the forces that animate nature
101 and the mutual positions of the beings that compose it, if this intellect were vast enough to submit the data
102 to analysis, could condense into a single formula the movement of the greatest bodies of the universe and
103 that of the lightest atom; for such an intellect nothing could be uncertain and the future just like the past
104 would be present before its eyes” (Laplace 1902).

105 In the 1950s, further formalizations of probabilistic causality appeared in the philosophical literature
106 (Salmon 1980). Good (1963) and Suppes (1970) attempted to identify the tendency of an event to cause
107 another by (1) constructing causal relations on the basis of probabilistic relations between events, (2)
108 employing the statistical relevance as the basic concept, and (3) assuming temporal precedence of causes
109 [see Russo and Williamson (2007) for a detailed account of probabilistic causality and of assumptions and
110 axioms]. Probabilistic causality “places emphasis upon the mechanisms of causality, primarily uses
111 concepts of process and interaction, and appeals to laws of nature” (Russo 2009).

112 In the 70s causality still remained as “one of the most important, most subtle, and most neglected of all
113 the problems of Statistic” (Dawid 1979). It is only with the pioneering work of Rubin on a formal
114 potential outcome/counterfactual analysis (Rubin 1974) that the statistical literature reconnects with
115 causality and establishes a statistical definition of causality. The work of Rubin gave momentum to the
116 development and application of statistical models, or cause-effect analysis techniques, which in the last
117 decades have expanded into various applications including the foundational statistical principles set in the
118 early work of Wright (1921) in the field of genetics.

119 **3 Approaches to causality research**

120 **3.1 Correlation studies and their limitations**

121 Cause-effect analysis techniques presented in this review enable answering three types of causal
122 questions: (1) identifying causes (i.e. *why* a singular event occurs), (2) assessing effects (i.e. the *what-if*
123 type of question, referred to the change in effect of some change in the cause), and (3) describing

124 mechanisms [i.e. *how* some effects follow from a certain cause (Holland 2003)]. Before we begin the
125 review of the mainstream approaches to causality research, here we provide a brief discussion on
126 correlation studies. As pointed out by many in the literature (Pearl 2000b), correlation and causation
127 should not be confused. Positive correlation may be defined probabilistically for two variables, X and Y
128 , as follows:

129 (1)
$$P(Y|X) - P(Y)P(X) > 0,$$

130 meaning that the probability that X and Y occur jointly is larger than the product of probabilities for each
131 occurring independently. Similarly, negative correlation, can be defined as:

132 (2)
$$P(Y|X) - P(Y)P(X) < 0,$$

133 and the two variables, X and Y are uncorrelated if:

134 (3)
$$P(Y|X) = P(Y)P(X).$$

135 Correlation typically indicates that whenever X occurs, there is a higher chance of observing Y . A well-
136 known example is that homelessness and crime rate are correlated, however, mere correlations do not
137 provide a scientific evidence of whether homelessness causes crime, or that crime causes homelessness
138 (Sugihara et al. 2012). The underlying cause could be another variable (e.g. unemployment) that may
139 influence both.

140 3.2 Randomized experiment

141 3.2.1 Statistical differences in the outcomes of experimental studies

142 Experimental randomized studies , in contrast to correlation studies, provide an ideal means to inferring
143 causality (Angrist and Pischke 2008).

144 In randomized experiments, individuals (or units) taken from a sufficiently large population are divided
145 into two subgroups: one in which individuals receive a treatment (treatment group), and one in which

146 individuals do not receive a treatment (control group). Let us consider the case, in which a large number
 147 of similar cities are randomly divided into two groups. One group enforces a road space rationing and the
 148 other does not. We can define $T_i = \{0, 1\}$, for all $i = 1, \dots, N$, as a binary random variable describing the
 149 treatment (e.g., enforcing a road space rationing or not enforcing a road space rationing). Let us define Y
 150 as the variable to be explained, or response variable, such as the urban air quality.

151 The observed outcome for an individual i , Y_i , can be written as:

$$152 \quad (4) \quad Y_i = \begin{cases} Y_{1i} & \text{if } T_i = 1 \\ Y_{0i} & \text{if } T_i = 0 \end{cases}$$

$$= Y_{0i} + (Y_{1i} - Y_{0i})T_i.$$

153 In order for equation (4) to hold, Rubin (1978, 1980) defines the so-called stable-unit-treatment-value-
 154 assumption (SUTVA). The assumption implies that “a causal effect of one treatment relative to another
 155 for a particular experimental unit is the difference between the result if the unit had been exposed to the
 156 first treatment and the result if, instead, the unit had been exposed to the second treatment” (Rubin 1978).
 157 SUTVA rests on the idea that the potential outcome of one participant is not affected by the treatment
 158 applied to another participant. For example, one city institutionalizing a road space rationing policy does
 159 not affect another city in the experiment. Furthermore, it assumes that for each unit there is a single
 160 version of each treatment level (i.e. only one type of road space rationing of equal efficacy is used by all
 161 cities under study). The assumption introduced by Rubin (1980) holds if the value of Y for any
 162 individual i exposed to a treatment T will be the same no matter what mechanism is used for the
 163 assignment of T to i for all individual participants and treatments (Rubin 1986) so that:

$$164 \quad (5) \quad Y_i(T_1, T_2, \dots, T_n) = Y_i(T_i).$$

165 The assumption is violated if multiple versions of the treatments or interferences (e.g. communication)
 166 between individual participants exist (Rubin 1986). The plausibility of the assumption has been subject

167 matter of a number of publications [we refer the reader to e.g. Sobel (2006) for more information on the
168 issue]. It is, however, notable that this assumption is hardly plausible in a policy context, where a policy
169 instrument is often modified or customized to the local or regional circumstances and policy outcomes are
170 often benchmarked or publicized widely, directly or indirectly affecting others in the experiment. We will
171 come back on this issue later in this review.

172 In the notation introduced in equation (4), Y_{0i} is the potential outcome for an individual i (e.g., air quality
173 index, AQI for city i) had the individual not been exposed to the treatment (e.g., road space rationing),
174 regardless of whether the individual is actually exposed to the treatment or not; whereas Y_{1i} is the
175 potential outcome had the individual been exposed to the treatment. In general, $Y_{1i} - Y_{0i}$ represents the
176 causal effect of T_i on Y_i at the individual level. However, it is not possible to observe both potential
177 outcomes simultaneously from any given individual (e.g., a particular city), since an individual is either
178 exposed to treatment or control, not to both at the same time. Therefore, the aggregate causal effects and,
179 in particular, the average causal effect (i.e. the average effect in the general population) is observed
180 instead in reality.

181 The observed difference in average outcome (e.g., AQI) between the treatment group (e.g., cities
182 enforcing road space rationing) and control (e.g., those not) can be expressed as

183 $E[Y_i | T_i = 1] - E[Y_i | T_i = 0]$. For example, if the average AQI of the cities that exercise road space
184 rationing is 5 and that for those not is 2 using a 1-to-10 quality scale (least to most severe pollution), the
185 observed difference in average outcome becomes 3, which can be interpreted as a worsening effect.
186 However, road space rationing is likely to be introduced to the cities with heavy traffic and air pollution
187 in the first place, and therefore the observed difference in the AQI between the two groups cannot be
188 directly translated into the causal effect of a road space rationing. This problem, referred to as ‘selection
189 bias’, is elaborated further in the next section.

190 3.2.2 Rubin's causal model

191 The expected outcome of a group of individuals who were not exposed to the treatment can be expressed
 192 as $E[Y_{0i} | T_i = 0]$. Using the same example, this term shows the AQI of the cities that did not use road
 193 space rationing. The expected outcome for group of individuals that were exposed to the treatment, had
 194 the group not exposed to the treatment can be expressed as $E[Y_{0i} | T_i = 1]$. For example, this term would
 195 show the average severity of air pollution measured in AQI of those cities that exercise road space
 196 rationing, if they had not taken such a measure. Suppose that a group of cities have been using road space
 197 rationing. Suppose, further, that one can reverse the time and let the same group avoid using road space
 198 rationing. If this were possible, $E[Y_{0i} | T_i = 1]$ would be the current average AQI of these cities after
 199 reversing the time. However, this term is obviously not measurable. If it were measurable and if the
 200 treatment is independent of potential outcomes (i.e. with T_i randomly assigned), the causal effect of the
 201 treatment, $E[Y_{1i} | T_i = 1] - E[Y_{0i} | T_i = 1]$, can be written as:

$$202 \quad (6) \quad \underbrace{E[Y_{1i} | T_i = 1] - E[Y_{0i} | T_i = 1]}_{\text{average treatment effect on the treated}} = \underbrace{E[Y_i | T_i = 1] - E[Y_i | T_i = 0]}_{\text{observed difference in response}} - \underbrace{E[Y_{0i} | T_i = 1] + E[Y_{0i} | T_i = 0]}_{\text{selection bias}}.$$

203 The term, $E[Y_{1i} | T_i = 1] - E[Y_{0i} | T_i = 1]$ represents the average causal effect of treatment for those who
 204 were treated (e.g., the difference in AQI as a result of using road space rationing). The term
 205 $E[Y_{0i} | T_i = 1] + E[Y_{0i} | T_i = 0]$ represents the selection bias (Angrist and Pischke 2008) that represents
 206 the fact that those who need treatment are more likely to seek treatment. For example, suppose that the
 207 average AQI of the cities that actually used road space rationing if they had not introduced road space
 208 rationing is 8, and that of those that did not is 2. In this case, the selection bias becomes $8 - 2 = 6$, and
 209 therefore the right-hand-side of the equation becomes $3 - 6 = -3$, meaning that the average road space
 210 rationing AQI improved on average by 3.

211 However, as noted earlier the term, $E[Y_{0i}|T_i = 1]$ cannot be directly observed or calculated. Therefore,
 212 one would have to find a counterfactual for this term in order to estimate the causal effect of the treatment
 213 in eq. (6) (Angrist and Pischke 2008). This can be obtained by the random assignment of i . Under the
 214 Rubin's causal model, the problem of spurious correlations discussed in the previous section can only be
 215 eliminated by using randomization of observations to the categories of a hypothesized causal factor (e.g.,
 216 treatment vs. control) or by using a method that somehow mimics randomization process [(Morgan 2013);
 217 see section 3.3.1]. Randomization reduces the chance of intentional or unintentional bias, and it allows for
 218 effects and errors due to 'unaccounted-for' variables to act randomly, rather than consistently, affecting
 219 the response across treatments (Shaffer and Johnson 2008).

220 For example, random assignment, or 'randomizing' can be achieved by choosing the treatment and
 221 control groups with statistically equivalent level of AQIs. Random assignment makes the treatment T_i
 222 independent of potential outcomes. In particular, T_i is independent of Y_{0i} , thus allowing us to swap the
 223 terms $E[Y_{0i}|T_i = 1]$ and $E[Y_{0i}|T_i = 0]$ in the following expression:

$$\begin{aligned}
 & E[Y_i|T_i = 1] - E[Y_i|T_i = 0] \\
 224 \quad (7) \quad & = E[Y_{1i}|T_i = 1] - E[Y_{0i}|T_i = 0] \\
 & = E[Y_{1i}|T_i = 1] - E[Y_{0i}|T_i = 1].
 \end{aligned}$$

225 Given random assignment, Eq. (7) can be further reduced to:

$$\begin{aligned}
 & E[Y_{1i}|T_i = 1] - E[Y_{0i}|T_i = 1] \\
 226 \quad (8) \quad & = E[Y_{1i} - Y_{0i}|T_i = 1] \\
 & = E[Y_{1i} - Y_{0i}].
 \end{aligned}$$

227 The relationship identified in eq.(8) contains no selection bias, thus signifying, for example, that whether
 228 each individual city in the population under study has instituted a road space rationing policy or not, it

229 does not affect the identification of the causal effect. The effect of a randomly-assigned road policy on the
230 city that implemented it is, in fact, the same as the effect of the road policy on a randomly chosen city.

231 3.3 Observational studies

232 For a while, much of the causality literature, in particular in the epidemiological, psychological and
233 educational sciences (Campbell and Erlebacher 1970), has implied that only properly randomized
234 experiments could lead to useful and trustable estimates of causal effects. However, as Rubin states
235 (1974), such contention would be untenable if taken as applicable to all fields of science, given that much
236 of the scientific development has been obtained for a big part of the past century without using
237 randomized experiments. The statement still holds today, since randomized experiments are only feasible
238 under certain conditions, and would probably be counter-productive in those contexts in which
239 observational data is not immediately available.²

240 Conceptually, there are two major criticisms to Rubin's model. First, as discussed earlier, it is impossible
241 to detect the individual causal effect, $Y_{1i} - Y_{0i}$, thus making the true causal effect impossible to detect
242 (Russo et al. 2011). Putting this into a practical context, the same person (or city) cannot simultaneously
243 take and not take a painkiller (or institute a policy) to observe the effect. In some cases, experiments can
244 be done for the same unit over time. Second, Rubin's model is confined to a *Platonic heaven* situation, in
245 which one can observe only average representations, rather than direct causal effects (Dawid 2007, p.
246 510).

247 At a more practical level, Rubin (1974) also noted that randomized studies cannot be widely applied
248 when: (a) the cost of performing the equivalent randomized experiment to test for all potential alternatives
249 (or treatments) is prohibitive; (b) there is a presence of ethical reasons according to which the treatments

² In their satire, Smith and Pell (2003) point out that the effectiveness of parachutes has never been proven using a randomized control trial.

250 cannot randomly assigned; or (c) the estimates based on the results from experiment indicate that it would
251 require several years to be completed (Rubin, 1974).

252 For these reasons, researchers rely on observational data, i.e. data that were not generated using an
253 experimental design. Observational data are obtained from surveys, longitudinal and panel data, censuses,
254 and administrative records, and can vary both temporally and spatially (Christman 2008). Observational
255 data are typically inexpensive to collect and are in plentiful supply (Iacus et al. 2012). Investigators using
256 observational data (i.e. from observational studies) share the common objective of devising causal
257 relations and, thus, face similar problems to *experimenters* (Cochran 2009). Complex interactions are also
258 present in observational studies and can greatly complicate the interpretation of effects, although they
259 reflect the inherent complexity of natural systems (Shaffer and Johnson 2008).

260 3.3.1 Matching methods and quasi-experimental designs

261 In the absence of a randomized experiment and when only observational data is available, cluster analysis
262 techniques such as matching (Stuart 2010) allow for harnessing the benefits of Rubin's model by equating
263 (or "balancing") the distribution of covariates in the treatment and control groups. Well-matched
264 organized samples of the treatment and control groups can achieve such goal. The methods aim to
265 replicate as closely as possible a randomized experiment, by pruning the observational dataset and
266 making sure that the empirical distributions of covariates are similar (Ho et al. 2006, Stuart 2010).
267 Treatment and control units are paired based on a number of observable pre-treatment covariates (i.e.
268 observable characteristics).

269 The individuals in a group are paired solely for the purpose of obtaining the best possible estimate of the
270 effect of a causal variable T_i on an observed outcome Y_i . Using matching, differences in outcomes for
271 units with different treatment levels but the same values for pre-treatment variables can be interpreted
272 causally (Yang et al. 2015). For example, matching could be based on the probability of T_i for each
273 individual i in the population, calculated as a function of Q_k , with $k = 1, \dots, V$, which represent the set of

274 background variables of interest, that is assumed to predict both T_i and Y_i (Morgan and Harding 2006).
275 The matching procedure will select only matched sets of treatment and control cases that contain
276 equivalent values for these predicted probabilities (Morgan and Harding 2006). The matching algorithm
277 allows selecting from the joint distribution of Q_{ik} and Y_i only the information that is related to the causal
278 variable (or treatment variable) T_i , and the procedure is conducted until the distribution of Q_{ik} is
279 equivalent for both the treatment and control cases, thus until the data are balanced, or matched (Morgan
280 and Harding 2006).

281 Matching methods do not directly allow for making causal inferences, since they are data-processing
282 algorithms not statistical estimators, thus they require the use of some type of causal estimator to make
283 such inferences [e.g. testing the difference in means between Y in the treatment and control groups; see
284 (Iacus et al. 2012)]. As Stuart (2010) points out, after the analyst has created treatment and control groups
285 with adequate balance, and designed the observational study, the analysis moves to the outcome
286 interpretation stage. At this stage, the analysis will typically be limited to techniques of regression
287 adjustment using matched samples and use regression-based techniques in combination with the matched
288 samples. Matching methods, in fact, are best used in combination with regression models (see section
289 3.3.2), instrumental variables models, or structural equation models [SEM (Ho et al. 2006)].

290 Matching techniques have been widely used in economics (Abadie and Imbens 2006), medicine
291 (Christakis and Iwashyna 2003), and sociology (Morgan and Harding 2006), among other fields of
292 science [see also (Sekhon 2011)]. Commonly used matching methods include difference-in-differences
293 matching (Abadie 2005), multivariate matching based on the Mahalanobis distance metric (Cochran et al.
294 1973), nearest neighbor matching (Rubin 1973), propensity score matching (Caliendo and Kopeinig
295 2008), genetic matching (Diamond and Sekhon 2012), and coarsened exact matching (Iacus et al. 2012)
296 [see (Stuart and Rubin 2008) for a review]. Quasi-experimental designs using the treatment and control

297 duality also include difference in differences techniques used with longitudinal data, for which we refer
298 the reader to (Abadie 2005, Athey and Imbens 2006, Donald and Lang 2007, Puhani 2012).

299 Observational studies become relevant if performed on all causally-important variables and on several
300 control groups that are each representative of a potentially different bias (Rubin 1974). Observational
301 studies do require the analyst to carefully study the process of data generation and the
302 treatment/assignment mechanism (Iacus et al. 2012). In observational studies without randomization the
303 analyst uses the design phase to help with approximating hypothetical randomized experiments. The so-
304 called identification strategy describes the manner in which a researcher uses observational data not
305 generated by a randomized trial to approximate a real experiment (Angrist and Pischke 2008). The use of
306 an observational study allows estimating the average effect on the treated (or ATT) and the average
307 treatment effect (or ATE), based on data availability (Stuart 2010).

308 3.3.2 Regression-based causality

309 SEM have become a core method for assessing causality in the social sciences, especially for research
310 questions that cannot be tackled by experimental testing (Pearl 2009). The variables of interest for causal
311 research are for this reason also called *latent variables*, because of their inaccessibility through direct
312 measurement without a substantial measurement error (Bollen 2002). In many cases, it is impossible or
313 too expensive to conduct controlled experiments, but SEM allows for discovery of likely causal relations
314 from observational data (Shimizu et al. 2006).

315 SEM can also be combined with graphical constructs that allow laying out the causal relationships under
316 analysis pictorially. A particular kind of graph used in causal analysis is the directed acyclic graph (DAG)
317 or Bayesian network (Pearl 1995, Morgan 2013). DAGs are visual representations of qualitative causal
318 assumptions and can be related to probability distributions linked to the data under study and to causal
319 frameworks.

320 Causal models are usually characterized by the presence of a set of explanatory variables or covariates X
 321 (i.e. the putative causes) and a response variable Y (i.e. the putative effect) in the form, for instance, of a
 322 simple structural equation:

$$323 \quad (9) \quad Y = \beta X + \varepsilon,$$

324 where β is the causal effect on Y for a one unit difference in X , representing the coefficient determining
 325 the extent of the influence of X on Y , and ε represents the errors, unmeasured factors, or all other
 326 influences on Y .

327 The interpretation of ε and β is not trivial. Error terms may be interpreted deterministically or
 328 epistemically (Russo 2009). In the first case, we may assume that errors represent the lack of knowledge
 329 of the analyst. Thus if complete knowledge would be in hand, a precise relationship, between X and Y ,
 330 could be determined without error. The SEM reports deterministic causal relations. In the epistemic
 331 acceptance of the concept, the SEM represents causal relations that are thought to be genuinely
 332 indeterministic, thus errors are to be modelled probabilistically (Russo 2009). This second acceptance is
 333 the one we hold in this review.

334 The parameter β has in the context of SEM a causal interpretation, thus it should quantify the extent of
 335 the causality. Thus, we can define (Russo 2009):

$$336 \quad (10) \quad \beta = r \frac{\sigma_X}{\sigma_Y}.$$

337 The correlation coefficient r can be calculated as the ratio between the covariance σ_{XY} and the variances
 338 σ_X and σ_Y :

$$339 \quad (11) \quad r = \frac{\sigma_{XY}}{\sigma_X \sigma_Y}.$$

340 Similarly, we may proceed and calculate all β_s and δ_s in the SEM.

341 Let us now consider the example below representing a generic bivariate regression equation:

342 (12)
$$Y = \alpha + \beta X + \varepsilon$$

343 where α is the intercept and ε is the error term. In a causal interpretation of Eq. (12) β represents the
344 structural causal effect that applies to all members of the population of interest. Thus, in addition to being
345 linear, this equation says that the functional relationship of interest is the same for all members of the
346 population. Logarithmic transformations or other functional transformations of the variables of interest in
347 the model can be typically considered (Baiocchi 2012). The ordinary least squares estimator of the
348 bivariate regression coefficient β is then (Morgan and Winship 2007):

349 (13)
$$\beta_{OLS} = \frac{\sigma_{YX}}{\sigma_X}$$

350 The above is just an example of the application of regression techniques for the estimation of the
351 regressors of interest. Regression techniques provide a good estimation of the causal parameters, if the
352 error terms in SEM are uncorrelated with the regressor (see assumptions in section 4.1). The coefficient of
353 determination r^2 may be used to evaluate the goodness of fit of the model. Example of regression
354 techniques include least squares and partial least squares techniques (Wold 1982, Angrist and Imbens
355 1995, Tenenhaus et al. 2005, Esposito Vinzi et al. 2010). In the next section we focus on the causal
356 interpretation of regression techniques and on the instrumental variable approach. Further applications of
357 regression-based techniques include regression-discontinuity designs, for which we refer the reader to
358 (Hahn et al. 2001, Imbens and Lemieux 2008, Lee and Lemieux 2010).

359 3.3.2.1 Causal interpretation of regressions

360 We focus on this section on the causal interpretation of regressions as estimators of causality. We refer
361 the reader to (Berk 2004, Gelman and Hill 2006, Morgan and Winship 2007, Angrist and Pischke 2008,

362 Freedman 2009, Hansen 2015) for a complete presentation of regression techniques and for a complete
363 analysis of the limitations of such approaches.

364 Regressions do not necessarily hold a causal interpretation, and they can be simply interpreted as a
365 descriptive tool or as “a technique to estimate a best-fitting linear approximation to a conditional
366 expectation function that may be nonlinear in the population” (Morgan and Winship 2007). However,
367 regression, if well specified, can provide information about the causal relation between X and Y . It is the
368 more ambitious question of when a regression has causal interpretation that concerns us in this review,
369 due to its applicability for complex systems under study for QSA. To arrive at a causal model from a
370 regression model, the analyst aims to study how one variable would respond, if one intervened and
371 manipulated other variables (Freedman 2009). This implies that the causal results from a regression-based
372 cause-effect analysis depend on the hypothesis framework of the analyst. It is within this framework that
373 causality can be determined.

374 Let us assume that X_i is a vector of covariates that are associated in some way with a response variable
375 Y . The conditional expectation function (CEF) of Y is denoted as $E[Y|X_i]$ and denoted as
376 $E[Y|X_i = x]$ for any realization x of X_i [see (Angrist and Pischke 2008) for a formal definition and
377 proof of theorems]. Least squares regression allows the calculation of a regression surface that is a best-
378 fitting linear-in-the-parameters model of $E[Y|X_i]$, thus of the association between Y and any
379 realization x of X_i , minimizing the average squared differences between the fitted values and the true
380 values of $E[Y|X_i = x]$ (Morgan and Winship 2007, Angrist and Pischke 2008).

381 A regression can be considered causal when the CEF it approximates is causal, or when the CEF
382 describes differences in average potential outcomes for a fixed reference population (Angrist and Pischke
383 2008). As discussed in section 3.2.1, experiments with random assignments ensure that the causal

384 variable of interest is independent of potential outcomes, thus the groups under comparison are effectively
385 comparable. A core assumption for the causal interpretation of regression, is the conditional independence
386 assumption [or CIA; see (Rosenbaum 1984, Lechner 2001, Angrist and Pischke 2008)], which is at the
387 basis of most empirical work in economics. The CIA is required for a regression to identify a treatment
388 effect. The experimental design introduced in section 3.2 ensures that the causal variable of interest is
389 independent of potential outcomes, which guarantees that the groups being compared are truly
390 comparable (Angrist and Pischke 2008). This notion can be embodied regressions that are causally
391 interpreted. CIA, also called as selection-on-observables, determines that the covariates to be held fixed
392 are assumed to be known and observed. As a consequence, according to this assumption the residual in
393 the causal model is uncorrelated with the regressors. Regression can be used as an empirical strategy to
394 turn the CIA into causal effects. Under CIA the covariates X_i are held fixed for the causal inference to be
395 valid. These control variables (or covariates) are assumed to be known and observed (Angrist and Pischke
396 2008).

397 Let us consider a generic causal model:

398 (14)
$$f_i(B) = \alpha + \rho B + \eta_i,$$

399 where B is a variable that can take on more than two values. The equation is linear and assumes the
400 functional relationship under consideration being the same for all individuals in the population under
401 study. Unlike the factor η_i that captures all unobserved factors determining the outcome for each specific
402 individual B is not indexed per individual. The causal model, therefore, tells us the extent of B for any
403 value of B and not for a specific realization B_i . We can further specify the causal model for the
404 individual case, thus we consider that the causal relationship between putative causes and response is
405 likely to be different for each individual, as in:

406 (15)
$$Y_i = \alpha + \rho B_i + \eta_i.$$

407 A classic example is that B_i could be the number of years of schooling for a certain individual and Y_i
 408 could represent the current salary for that individual (Angrist and Krueger 1992). Eq. (15) is similar to a
 409 bivariate regression model. However, it is Eq. (14) that explicitly associates in the model constructed by
 410 the analyst the coefficients in Eq. (15) with a causal relationship, thus establishing the causal association.
 411 The causal model determines that B_i may be correlated with $f_i(B)$ and the residual term η_i .

412 We can, then, consider the vector of covariates X_i' . The random residual part of Eq.(15) η_i can be
 413 decomposed under CIA into a linear function of observable characteristics X_i' and an error term u_i :

$$414 \quad (16) \quad \eta_i = X_i' \gamma + u_i,$$

415 where γ is a vector of population regression coefficients that satisfies the relationship $E[\eta_i | X_i] = X_i' \gamma$.

416 The vector γ is defined by the regression of η_i on X_i , thus the residual u_i and X_i' are uncorrelated by
 417 construction [see (Angrist and Pischke 2008) for further details and proof of concept]. By virtue of CIA,
 418 we can define (Angrist and Pischke 2008):

$$419 \quad (17) \quad E[f_i(B) | X_i, B_i] = E[f_i(B) | X_i] = \alpha + \rho B + E[\eta_i | X_i] = \alpha + \rho B + X_i' \gamma.$$

420 We can re-write the causal model as:

$$421 \quad (18) \quad Y_i = \alpha + \rho B_i + X_i' \gamma + u_i.$$

422 The residual in the causal model is uncorrelated with the regressors B_i and X_i , thus ρ effectively
 423 represents the causal effect of interest, allowing for the attribution of causal meaning to the regression.
 424 The selection of the right set of control variables is the subject of an extensive literature. We refer the
 425 reader to Angrist and Krueger (2001) and Angrist and Pischke (2008) for a detailed analysis of the matter.

426 **3.3.2.2 Instrumental variables and causality**

427 We have just seen how regressions can be causally interpreted within the boundaries of a specific model.

428 A major complication is the possibility that regressors and errors [e.g., B_i , X_i , and U_i in the example in

429 Eq.(18)] are correlated, thus undermining the statistical validity of the model. Under such condition,

430 regression estimates would lose their causal interpretation. For the causal interpretation to hold, the

431 regressors have to be asymptotically uncorrelated with the errors or residuals. The potential inconsistency

432 is determined by the fact that changes in B_i are not only associated with changes in Y_i but also with

433 changes in U_i .

434 We consider that the potential outcomes can be written as (Angrist and Pischke 2008):

435 (19)
$$Y_i = \alpha + \rho B_i + A_i' \gamma + U_i.$$

436 Here A_i' is a vector of control variables, which unlike X_i in the example in Eq. (18) is unobserved.

437 Instrumental variable methods (Heckman and Vytlacil 2001, Newey and Powell 2003, Firebaugh 2008,

438 Bollen 2012) allow the analyst to introduce an instrumental variable, say Z_i , that is correlated with the

439 causal variable of interest B_i , and uncorrelated with both A_i' and U_i , such that $E[Z_i U_i] = 0$. Such a

440 condition is a special case of CIA introduced in the previous section. In this case it is the instrumental

441 variable Z_i that is independent of potential outcomes, rather than the variable of interest B_i . It follows

442 then that the causal effect ρ can be expressed as (Angrist and Pischke 2008 chap. 4):

443 (20)
$$\rho = \frac{\frac{\sigma_{Y Z_i}}{\sigma_{Z_i}}}{\frac{\sigma_{B_i Z_i}}{\sigma_{Z_i}}}.$$

444 The equality in Eq. (20) is verified if:

- 445 • Z_i has a clear effect on B_i ;
- 446 • Z_i affect Y_i only by means of the causal variable B_i ;
- 447 • Z_i is independent of potential outcomes, so it is as good as if randomly assigned.

448 The consideration of instrumental variables allows for the causal interpretation of ρ . Instrumental
449 variables are identified case by case from the processes determining the variable of interest. For the
450 example of the relationship between schooling level and earnings, Angrist and Krueger (1992) used the
451 school start age of pupils as an instrumental variable. Instrumental variables solve the problem of missing
452 or unknown controls. In many cases, in fact, the necessary control variables are typically unmeasured or
453 simply unknown. In the absence of suitable instrumental variables in the system the causal framework
454 does not hold.

455 There are some recognized pitfalls of the instrumental variable approach (Morgan and Winship 2007). In
456 some cases the assumption that the instrumental variable does not have a direct effect on the response
457 variable may be too strong. Even when such condition is verified, an instrumental variables estimator is
458 biased in a finite sample (Morgan and Winship 2007). These pitfalls may influence the possibility
459 of drawing causal inference from the results of a study (see section 4.1). The limitations of regression-
460 based methods should be carefully considered for the causal analysis to be valid. A causal regression may
461 be invalidated by omitting variables that both affect the dependent variable and are correlated with the
462 variables that are studied in the causal regression model, by the way missing data is handled, and by the
463 presence of potential biases determined by measurement errors (Allison 1999).

464 3.3.3 Applications

465 We survey here the application of regression-based techniques and combined matching and regression
466 techniques in the field of sustainability.

467 Empirical analyses using causal regression techniques have been widely applied to study the relationship
468 between trade openness, economic development and environmental quality (Stern 2004, Copeland and
469 Taylor 2013). In the Environment Kutznets Curve literature, a considerable amount of studies deal with
470 this relationship, treating environmental degradation measures as the dependent variables and income as
471 the independent variable, and providing mixed results (Soytas et al. 2007).

472 Antweiler et al. (1998) find that international trade, although altering the pollution intensity of countries,
473 creates small changes in pollution concentrations, especially of SO₂. The authors find evidence that both
474 environmental regulations and capital-labor endowments determine SO₂ concentrations and conclude that
475 openness and freer trade appear to be good for the environment. The study concludes that if an increase in
476 trade openness generates a 1% increase in income and output then, as a result of scale and technology
477 pollution does fall by approximately 1%. Cole and Elliott (2003) confirm both environmental regulation
478 effects and capital-labor effects for SO₂ and suggest that these results do not necessarily hold for other
479 pollutants, such as NO_x, biochemical oxygen demand (BOD) and CO₂, for which an increase in emissions
480 is likely to happen as a result of freer trade.

481 Frankel and Rose (2005) study the effect of trade on the environment and use exogenous geographic
482 determinants (i.e., lagged income, population size, rate of investment, and human capital formation) as
483 instrumental variables to account for the endogeneity of trade. The authors conclude that trade appears to
484 have a beneficial effect on some measures of environmental quality. In particular, they conclude that trade
485 significantly tends to reduce the concentrations of SO₂ and NO₂. Managi et al. (2009) find that trade is
486 beneficial for OECD countries, while it has detrimental effects on SO₂ and CO₂ concentrations in non-
487 OECD countries. A lower BOD is found in non-OECD countries. The detrimental impact is found to be
488 larger in the long term, rather than in the short term.

489 A bulk body of research regards the accumulation of greenhouse gases (GHGs) in the atmosphere leading
490 to climate change. Regression techniques of econometric inspiration are commonly applied for the study
491 of the influence of climate change on a number of endpoints. The matter of adaptation under climate

492 change is analyzed using nonlinear regression in Schlenker and Roberts (2009). The author controls for
493 precipitation, technological change, soils, and location-specific unobserved factors, and the results show a
494 nonlinear relationship between temperature and soil yields. The relationship between mortality and
495 changes in daily temperatures is described using regression techniques in Barreca et al. (2013). The
496 authors document a remarkable decline in the mortality effect of temperature extremes in the 20th century
497 in the United States, and point to air conditioning as a central determinant in the reduction of mortality
498 risks associated with extreme temperatures. The exposure to extreme temperatures determined by climate
499 change is linked to deleterious effects on fetal health, the decrease in birth weight, and an increase in the
500 probability of low birth weight in Deschenes et al. (2009 p. 216). The analysis rests on a number of strong
501 assumptions about data, including that the climate change predictions used in the regression model are
502 correct. In a similar fashion, climate policy has been linked to increase in mortality and migration
503 (Deschenes and Moretti 2009), fluctuations in the labor markets (Deschenes 2010), and reduced profits
504 from agriculture in the United States (Deschenes and Greenstone 2007) and in California (Deschenes and
505 Kolstad 2011). Conflicts and social instability have also been associated with climate change (Homer-
506 Dixon 1991). Earlier studies have shown that random weather events, such as drought and prolonged heat
507 waves, might at times be correlated with armed conflict in Africa (Miguel et al. 2004, Smith et al. 2007,
508 Burke et al. 2009). Hsiang et al. (2011) show that a causal link between temperature and conflict does
509 exist at various scales for relatively richer countries as well. The issue of causal links between climate and
510 conflict is contentious (Cane et al. 2014, Raleigh et al. 2014). Buhaug (2010 p. 16480) investigated the
511 scientific base of the claims and concluded that “a robust correlational link between climate variability
512 and civil war do not hold up to closer inspection” when alternative statistical models and alternative
513 measures of conflict are used. Hsiang and Meng (2014) reproduced the analysis of Buhaug (2010) and
514 corrected the correct the statistical procedure for model comparison. The study concludes that the claim of
515 Buhaug (2010) is inconsistent with the evidence presented, thus climate change does affect conflicts in
516 Africa (Hsiang and Meng 2014).

517 The potential sustainable impacts of fair trade, eco-certification and eco-labelling have been amply
518 studied using matching techniques in combination with regression techniques. Ruben et al. (2009) use
519 data from coffee and banana co-operatives in Peru and Costa Rica and find, using propensity score
520 matching, that fair trade improves access of farmers to credit and investments, and also affects their
521 attitude towards risk. The participation in a fair trade system improved employment, as well as their
522 bargaining power and trading conditions. The difference-in-differences identification strategy is used by
523 Hallstein and Villas-Boas (2013) to test the efficacy of eco-labels in promoting sustainable seafood
524 consumption. The study finds evidence that in a sample of ten stores in the San Francisco Bay area the
525 implementation of an eco-label led to a significant decline in sales in the range of 15%-40% of certain
526 classes of products with limited environmental sustainability. Miller et al. (2011) use difference-in-
527 differences to test the impact of a scheme of cash transfer on food security in Malawi. The study presents
528 evidence that food security is improved by the transfer of cash by the government to rural households in
529 Malawi. Eco-certification is also the subject of the study of Blackman and Naranjo (2012). The study uses
530 propensity score matching to control for selection bias and tests the impact of eco-certification on a high-
531 value agricultural commodity, organic coffee from Costa Rica. The study finds that organic certification
532 improves the environmental performance of coffee growers by reducing the use of chemicals and
533 improving the environmental performance of management practices.

534 Matching techniques have been used also to check progress on poverty reduction and on other goals in the
535 Millennium Development Goals (Sachs and McArthur 2005). Maertens et al. (2011) use a variety of
536 matching techniques to test the impact of globalization on poverty reduction in Senegal. The study finds a
537 significant positive impact of globalization on poverty reduction through employment creation and labor
538 market participation. Setboonsarng and Parpiev (2008) test the impact of microfinance on the MDGs
539 using data from a microfinance institution in Pakistan. Using difference-in-differences, the study finds
540 that the lending program of the institution contributed to income generation activities that have a
541 beneficial impact on the MDGs. Arun et al. (2006) use propensity score matching to test whether

542 microfinance reduces poverty in India and show that microfinance institutions have a significantly
543 positive effect on poverty reduction. Arnold and co-authors (2010) draw on the potential outcome model
544 for causal inference and use a matched cohort to test the relationship between health and development. In
545 a matched sample of 25 villages in rural India the study finds a positive influence on health from new
546 toilet construction, while no impact was found from height-for-age.

547 In the field of sustainable fisheries, Costello et al. (2008) apply propensity score matching to evaluate the
548 benefits of tradable harvest quotas (i.e. catch shares) on preventing the collapse of global fish resources.
549 The study finds that the implementation of catch shares halts, and even reverses, the global trend toward
550 widespread collapse of fish resources. The results are confirmed using propensity score matching by the
551 same research group (Costello et al. 2010).

552 Quasi-experimental designs have been used to evaluate the biodiversity and social impacts of
553 conservation and protection practices. Linkie et al. (2008) evaluate the impact of protected area on the
554 conservation of species in a large protected area in Indonesia. The study uses propensity score matching
555 to compare the deforestation rates in villages around the protected area and villages not around the area.
556 The study finds no evidence of a positive effect of the protected area on the reduction of deforestation.
557 Nelson and Chomitz (2011) test the impact of protected areas in reducing fires in tropical forests in
558 various regions. The study finds that protected areas substantially reduced fire incidence in Latin
559 America, Asia, and Africa. Matching criteria in this study included the distance to road network, distance
560 to major cities, elevations and slope, and rainfall. Andam and co-authors (2008) apply matching methods
561 to evaluate the impact on deforestation of Costa Rica's renowned protected-area system between 1960
562 and 1997. The institution of protected areas reduces deforestation and 10% of forests would have
563 disappeared without being protected. Ferraro and Hanauer (2014) use a quasi-experimental design to
564 study the mechanisms through which the policies of establishing protected areas affect social and
565 environmental outcomes. The authors analyze the causal effects of ecosystem conservation programs on
566 environmental and social outcomes, by focusing on the mechanisms determining variations that arise in a

567 certain area after land-use restrictions have been put in place. The study uses an asset-based poverty index
568 developed by Andam et al. (2010) and investigates the effect of protected areas on this index. Therefore,
569 the population is divided into treatment and treated group, respectively the causal effect of protected areas
570 and the people living around protected areas. After controlling for potential confounding variables and
571 biases, the authors conclude that two-thirds of the poverty reduction in Costa Rica can be causally
572 attributed to opportunities afforded by tourism, while changes in infrastructure or land cover had a little
573 causal influence on the outcome.

574 3.4 Time-series methods

575 3.4.1 Granger-causality

576 The vast availability of time-series data has given rise to a plethora of methods aimed at understanding
577 complex systems through studying their evolution in time. Time-series refer to data observed over a
578 number of discrete time-steps. In such cases, one may assume that causes both precede and help predict
579 their effects. We credit Wiener (1956) with the intuition that the causality of a (time-series) variable in
580 relation to another can be measured by how well one variable helps to predict the other. We can say that
581 variable Y ‘causes’ variable X if the ability to predict X is improved by incorporating information
582 about Y in the prediction of X . The concept was later formulated by Granger (1969), leading to the
583 establishment of the Wiener-Granger framework of ‘causality’. Geweke made several other important
584 contributions to the concept (Geweke 1982, 1984).

585 Let us consider two variables X and Y . We can say that X does not cause Y if the conditional
586 distribution of the effect Y only depends on the past history of Y itself and not on the past history of the
587 putative cause X .

588 Let us consider the history of X and Y , respectively $\{X\}$ and $\{Y\}$

$$\begin{aligned}
 \{X_t\} &= (X_t, X_{t-1}, X_{t-2}, \dots, X_L) \\
 \{Y_t\} &= (Y_t, Y_{t-1}, Y_{t-2}, \dots, Y_L)
 \end{aligned}
 \tag{21}$$

with L representing the number of time lags.

According to GC we say that X does not *Granger-cause* Y if Y_t only depends on its history but not on the history of X , alternatively expressed as (Granger 1969):

$$P(Y_t | X_{t-1}, Y_{t-1}) = P(Y_t | Y_{t-1}).$$

No relevant information can be extracted from the history of X to assess the effect Y , thus the predictability of Y does not increase if X is part of the universe of possible causative variables.

Conversely, if X Granger-causes Y , one can generally say that the past of X contains information that helps predict the future of Y .

GC models typically use vector auto-regression (VAR) models to analyze multivariate time-series. VAR models are simple constructions in which the value of a variable at a particular time is modeled as a linear weighted sum of its own past and of the past of a set of other variables. Each variable is a vector stochastic process representing a time-series. The structure of the VAR model provides information about the forecasting ability of a variable or of a group of variables. Therefore, GC does not directly imply true causality, but rather only implies forecasting ability (Zivot and Wang 2006).

Operationally, GC analysis rests on estimating and comparing the VAR models, given a set of time-series data. Let us expand our example consider a third variable Z together with X and Y . We are still interested in measuring whether X Granger-causes Y . The analysis starts with the joint estimation of a full VAR model for all the variables. A prediction/estimation error is computed for all the variables in the set (Seth et al. 2015). A second VAR model is then estimated, omitting X from the universe of all possible causative variables. For each remaining variable a new set of prediction/estimation errors is

610 calculated. If the prediction/estimation error for Y is significantly smaller for the full regression
 611 including X , then we may confidently state that X Granger-causes Y , conditioned on Z . As reported in
 612 (Seth et al. 2015), the magnitude of the GC is given by the ratio of the variance of the prediction-error
 613 terms for the reduced regression and the full regressions.

614 The standard test of GC developed by Granger (Granger 1969) is based on a linear regression model:

$$615 \quad (23) \quad Y_t = a_0 + \sum_{k=1}^L b_{1k} Y_{t-k} + \sum_{k=1}^L b_{2k} X_{t-k} + \xi_t,$$

616 where ξ_t are uncorrelated random variables with zero mean and variance σ^2 , L is again the specified
 617 number of time lags, and the time is $t = L + 1, \dots, S$. The null hypothesis that X_t does not Granger
 618 cause Y_t is supported when $b_{2k} = 0$ for $k = 1, \dots, L$, thus allowing Eq. (23) to reduce to:

$$619 \quad (24) \quad Y_t = a_0 + \sum_{k=1}^L b_{1k} Y_{t-k} + \xi_t.$$

620 Test statistics that can be applied to test the hypothesis are reported in Hlaváčková-Schindler et al. (2007).

621 GC has a number of useful properties [see e.g. (Geweke 1982, Seth et al. 2015)], including that VAR
 622 models may be estimated using relatively simple computation algorithms (e.g. ordinary least squares).

623 Furthermore, the analyst needs to make only minimal assumptions about the underlying physical
 624 mechanisms linking the variables under study as long as they rest on data that is suitable for VAR
 625 modelling. GC is based on the comparison of model errors; therefore, the analysis is applicable only to
 626 the case of stochastic variables, i.e. variables that can be modelled as having random variations, and to
 627 data that have variance and mean that are stable over time (Geweke 1984).

628 A number of limitations, including those identified by Granger himself (Granger 1969), are applicable to
 629 GC. Strictly speaking, what GC establishes is the fact that one event happens before another, which may
 630 or may not provide an evidence of a cause-effect relationship between them (Hu et al. 2011). GC is

631 typically a bivariate procedure in 2-dimensional systems. In. In the presence of a third variable that
632 commonly causes changes in the two variables with a different time-lag, the model may falsely recognize
633 the relationship between the two variables as a GC. Limitations of the approach also include the
634 inapplicability of GC in the presence of non-linear, contemporaneous causal links (Russo 2009). A
635 number of approaches have been developed to test for the strength of GC [see e.g. [see e.g. (Dolado and
636 Lütkepohl 1996, Zapata and Rambaldi 1997, Clarke and Mirza 2006)].

637 3.4.2 Convergent Cross Mapping in dynamic nonlinear systems

638 A number of methods extended the Granger's concept to non-linear cases [see e.g. Ancona et al. (2004)
639 for nonlinear bivariate time series; Baek and Brock (1992), Hiemstra and Jones (1994) for non-parametric
640 GC]. We refer to Hlaváčková-Schindler et al. (2007) for a thorough analysis of these methods and to Hu
641 et al. (2011) for further methodological expansions that address limitations of GC

642 GC may also give ambiguous results in deterministic settings, especially for dynamic systems with weak
643 to moderate coupling (Sugihara et al. 2012). The assumption of separability (see section 4.1) is not
644 satisfied in such systems. In this case, as noted by Sugihara et al. (2012), if X is a cause for Y ,
645 information about X will be redundantly present in Y and, as a consequence of Takens' theorem (Takens
646 1981), removing X from the universe of all possible causative variables would not remove the
647 information carried by X .

648 Work from Sugihara and co-authors (Deyle and Sugihara 2011, Sugihara et al. 2012, Clark et al. 2015)
649 addresses the limitations of GC for the case of (1) non-separable systems, (2) weakly coupled variables,
650 and (3) a presence of interactions among variables from external driving variables (e.g. ecological
651 variables such as species from temperature, precipitation, and upwelling). The applications demonstrated
652 in Sugihara et al. (2012) are particularly interesting to understand causality in dynamic systems that are
653 common in ecology (e.g. predator-prey systems).

654 For the case of dynamic systems, time-series variables can be considered causally linked if they belong to
 655 the same dynamic system (Takens 1981, Deyle and Sugihara 2011, Sugihara et al. 2012). Under such
 656 consideration, each variable can identify the state of the other, thus information about the past of one
 657 variable can be recovered from the time-series of the other, and vice versa (Sugihara et al. 2012).

658 Let us consider again two time-series of length L :

$$659 \quad (25) \quad \begin{aligned} \{X_t\} &= (X_t, X_{t-1}, X_{t-2}, \dots, X_L) \\ \{Y_t\} &= (Y_t, Y_{t-1}, Y_{t-2}, \dots, Y_L). \end{aligned}$$

660 X and Y are said to be causally linked if they share the same common attractor manifold M , thus if
 661 they are part of the same dynamic system (Sugihara et al. 2012). The manifold can be defined as the
 662 system of coordinates constructed from lagged coordinates of the time-series variables, of X and Y
 663 using the history of the variables as defined in Eq.(25). Following Takens' theorem (Takens 1981), we
 664 can reconstruct the value of the manifold M from a single observation variable of the system. Thus, we
 665 can generate a system of coordinates in the attractor manifold built from X , M_X , and a system of
 666 coordinates built from Y , M_Y . The convergent cross mapping [CCM; see (Sugihara et al. 2012, Clark et
 667 al. 2015, Ye et al. 2015) for a thorough analysis] approach tests for causality by measuring the extent to
 668 which the historical record of Y values can reliably estimate states of X . Using CCM, the analyst can test
 669 at a time t whether points located closely (i.e. with similar coordinates in the manifold) in M_Y can be
 670 used to identify closely-located points in M_X (Sugihara et al. 2012). Using a nearest-neighbor algorithm
 671 (Sugihara and Mayf 1990) CCM allows attributing weights to points in the manifold M_X and estimating
 672 the value of Y using these weights, thus estimating the quantity $Y|M_X$. Finally, the causal effect can be
 673 estimated by measuring the correlation between Y and $Y|M_X$ (McCracken and Weigel 2014). If high
 674 correlation is measured, the analyst may confidently use Y to estimate X or vice versa. Time-series

675 variables that are mutually coupled, in fact, allow for cross-mapping estimations in both directions, thus
676 each variable can be estimated from the other.

677 CCM can also accommodate for the case of time-series variables that do not interact with each other, but
678 which are both driven by a common variable. Information about the common cause, e.g. Z , can still be
679 recovered from X and Y . Such application is of particular interest for the study of non-dynamic and
680 chaotic variables. Increasingly data availability estimates improve in accuracy, thus implying
681 convergence in CCM and declining estimation error when cross-mapped estimates are calculated
682 (Sugihara et al. 2012).

683 3.4.3 Causality as information flow through transfer entropy

684 As described in the previous sections, GC measures causal influence statistically based on prediction by
685 means, e.g. of a VAR in stochastic systems with separability, and CCM deals with dynamical systems
686 where causal variables have synergistic effects. More recently, transfer entropy [TE; (Schreiber 2000a,
687 Runge et al. 2012, Gencaga et al. 2015, Gómez-Herrero et al. 2015)] has gained traction, finding
688 application in a wide range of fields [see e.g. (Katura et al. 2006, Wibral et al. 2013, Lehnertz and
689 Dickten 2015)]. TE is an information-theoretic measure of the time-directed information flows between
690 jointly dependent processes (Barnett and Seth 2014). Of particular interest is the application of TE to
691 quantify the information flow or information transfer within complex and dynamic systems (Runge
692 2015). The application of TE is especially suitable for systems for which only time-series of
693 measurements are available and for which the underlying mechanisms that would be needed to directly
694 infer causal relations are poorly understood.

695 Still bearing in mind the idea of Wiener earlier reported, one would expect the relationship between two
696 variables X and Y to be asymmetric and that the information flows in a direction from the source Y to
697 the target X (Razak and Jensen 2014). TE is a measure of such directed information transfer between
698 joint processes. TE is asymmetric, so that $TE(X \rightarrow Y) \neq TE(Y \rightarrow X)$. The difference indicates a

699 direction of information flow, which can be considered as a measure of potential causation from X to Y
 700 (Boba et al. 2015). In contrast with GC, TE is not framed in terms of prediction but in terms of resolution
 701 of uncertainty (Barnett et al. 2009). Therefore, $TE(Y \rightarrow X)$ is the degree to which Y provides
 702 information to disambiguate the future of X (i.e. to reduce the level of uncertainty on the future of X)
 703 beyond the degree to which X already disambiguates its own future (Barnett et al. 2009).

704 At the basis of TE is the notorious concept of differential entropy for a continuous random variable
 705 introduced by Shannon (Shannon 2001). Shannon's theorem is a very general way of characterizing the
 706 statistical dependency or shared information between two variables. Following the theorem, differential
 707 entropy is defined as:

$$708 \quad (26) \quad H(X_i = x) = - \int p(x) \log_2 p(x) dx.$$

709 The discrete version of Eq. (26) can be defined for a discrete random variable X with a domain of
 710 definition D_X , having possible values \mathcal{X} with probability $p = p(x)$ (Boba et al. 2015). The value of the
 711 entropy $H(X)$ measures the average amount of information gained from a measurement that specifies
 712 one particular value \mathcal{X} :

$$713 \quad (27) \quad H(X_i = x) = - \sum_{x \in D_X} p(x) \log_2(p(x)).$$

714 The entropy of X can be seen as a measure of the uncertainty of X (Hlaváčková-Schindler et al. 2007).
 715 We use \log_2 and \log interchangeably hereafter.

716 Let us consider again two random variables, X and Y , whose probability distributions are p_x and p_y ,
 717 and whose outcomes are from a set $D := D_x \cap D_y$. The interdependence between X and Y can be
 718 calculated using the Kullback-Leibler divergence (Kullback and Leibler 1951):

$$719 \quad (28) \quad D_{KL}(p_X|p_Y) = \sum_{x \in D} p_X(x) \log \frac{p_X(x)}{p_Y(x)}.$$

720 The concept of entropy rate H_r of a process was developed by Schreiber (Schreiber 2000b) to include a
 721 direction of the information flow and a chronological ordering. As in Boba et al. (2015), we may assume
 722 that time intervals τ are equidistant and use counters like $n := \lfloor t / \tau \rfloor$ to enumerate the time points. H_r can
 723 be, then, defined as:

$$724 \quad (29) \quad H_r = - \sum_{x_{n+1}, x_n^m} p(x_{n+1}, x_n^m) \log [p(x_{n+1} | x_n^m)].$$

725 In the formulation, x_n^m is an m -tuple of measurements at time steps $n, n-1, \dots, n-m+1$. Let us employ
 726 the same history length m for both data sets x_n and y_n , and, thus, define TE as (Schreiber 2000b):

$$727 \quad (30) \quad TE(Y \rightarrow X) = \sum p(x_{n+1}, x_n^m, y_n^m) \log \frac{p(x_{n+1} | x_n^m, y_n^m)}{p(x_{n+1} | x_n^m)}.$$

728 According to Lizier and Prokopenko (2010), TE can be viewed as ‘a conditional mutual information, [...]
 729 the average information in the source about the next state of the destination that was not already contained
 730 in the destination’s past states’. TE is a directional, dynamic measure of information transfer, but still
 731 remains a measure of observed (conditional) correlation rather than direct effect (Lizier and Prokopenko
 732 2010). TE can be considered as a nonlinear generalization of GC for the case of Gaussian variables (i.e.
 733 normally-distributed), and a formal link between GC and TE can be found in Barnett et al. (2009).
 734 Conversely, one can define GC as an approximation to TE (Schreiber 2000a), which is exact for Gaussian
 735 variables. The equivalence between GC and TE means that the former can be interpreted in terms of
 736 information-theoretic bits-per-unit-time (Barnett et al. 2009).

737 3.4.4 Applications

738 3.4.4.1 Granger-causality

739 The study of the GC between energy consumption, income and climate in countries of the globe is a well-
740 studied topic (Wagner et al. 2016). The application of the method allows for using a time-series approach
741 to study the dynamic link between CO₂ emissions and income. The approach allows for including in the
742 analysis the temporal component of the relationship between the emissions and economic growth, unlike
743 the case previously introduced on causal regression-based techniques. Methodological issues and
744 inconsistencies with the application of GC in this context are well-documented (Bruns et al. 2014).

745 Omri et al. (2014) test the causality between CO₂ emissions, economic growth, and foreign direct
746 investment (FDI) using panel data for a global panel of 54 countries over the period 1992-2011. The
747 authors prove a bidirectional GC between FDI and CO₂ for all countries, except for those in Europe and
748 North Asia. The study also finds a unidirectional GC between CO₂ and economic growth, except for the
749 analyzed countries in the Middle East, North Africa, and sub-Saharan Africa, for which a bidirectional
750 causality cannot be rejected. Pao and Tsai (2011a) analyze the period between 1992 and 2007 for the
751 causality between CO₂ emissions, energy consumption, FDI, and GDP in Brazil, Russian Federation, India
752 and China. The authors suggest that emissions are highly responsive to change in both energy
753 consumption and GDP, but not in FDI. Furthermore, the authors find a unidirectional causality from
754 energy consumption to emissions and a bi-directional GC between emissions and FDI.

755 Soytas et al. (2007) use a time-series of data for the period 1960-2004 and show that income does not
756 Granger-cause carbon emissions in the U.S. in the long run, but energy use does, thus revealing that a
757 decreased energy use can reduce carbon emissions. Chiou-Wei et al. (2008) use linear and nonlinear GC
758 to test the relationship between energy consumption and economic growth for a sample of Asian newly
759 industrialized countries and the U.S.. The study supports the neutrality hypothesis for the U.S., Thailand
760 and South Korea. A unidirectional causality from economic growth to energy consumption is found
761 between the Philippines and Singapore, while energy consumption may have affected growth in Taiwan,

762 Hong Kong, Malaysia and Indonesia. Menyah and Wolde-Rufael (2010) examine the causal relationship
763 among CO₂ emissions, renewable and nuclear energy consumption, and real GDP for the U.S. during the
764 period 1960–2007. The test results indicate no causality from renewable energy to CO₂ emissions and a
765 unidirectional causality from nuclear energy consumption to CO₂ emissions.

766 For the case of Central America, Apergis and Payne (2009) show that energy consumption and economic
767 growth Granger-cause CO₂ emissions, and that there is a bivariate causality between energy consumption
768 and CO₂ emissions. Long et al. (2015) investigate the relationships between energy consumption, carbon
769 emissions and economic growth in China from 1952 to 2012. The study finds a bivariate causality
770 between GDP and CO₂ emissions and between GDP and coal, gas, and electricity consumption, thus
771 suggesting that a change in the energy consumption structure of China would be required to meet climate
772 goals. Acaravci and Ozturk (2010) show that there is evidence of a causal relationship between energy
773 consumption, income and carbon emissions in Denmark, Germany, Greece, Iceland, Italy, Portugal and
774 Switzerland. Halicioglu (2009) indicates that, for the case of the country of Turkey, GC runs in both
775 directions between CO₂ emissions and income both in the short term and long term. The authors, thus,
776 state that it is possible to forecast the future levels of these variables from the past levels of each other.
777 Ang (2008) confirms the existence of a causality running from economic growth to energy consumption
778 growth, both in the short-run and the long-run, for the country of Malaysia. GC is verified in this context
779 also for the case of ASEAN-5 countries [Malaysia, Indonesia, Singapore, the Philippines and Thailand
780 (Chandran and Tang 2013)], Tunisia (Fodha and Zaghdoud 2010), India (Ghosh 2009), and Brazil (Pao
781 and Tsai 2011b).

782 A number of studies used GC to test the relationship between urbanization and carbon emissions. Hossain
783 (2011) finds no evidence of causality in the short and long run for nine emerging industrialized countries
784 for the period 1971-2007. Al-mulali et al. (2012) study 19 countries and find a positive causal relationship
785 between urbanization and CO₂ emissions in 84% of the cases. The same groups confirm these results for
786 the middle eastern and north African countries in the MENA group for the years 1980-2009 (Al-mulali

787 and Fereidouni 2013). Long-run bidirectional causality is found between urbanization and electricity
788 consumption in a study by Liddle and Lung (2014) on 105 countries for the period 1971-2009. Wang et
789 al. (2016a) find that urbanization Granger-causes carbon emissions in the long- and short-run for the
790 ASEAN countries and for the BRICS (i.e. Brazil, Russia, India, China and South Africa) countries (Wang
791 et al. 2016b) within the period 1985–2014.

792 GC has found applications also in the field of climatology. GC is here used to test the connection between
793 atmospheric CO₂ concentrations and global mean temperature. Young et al. (1991) show a causal
794 relationship between atmospheric CO₂ concentrations and global sea surface temperatures. Sun and Wang
795 (1996) suggest that global surface temperature Granger-causes global CO₂ emissions, but past
796 temperatures do not significantly improve the predictability of current CO₂ concentrations. Tol and De
797 Vos (1998) demonstrate that there is a robust statistical relationship between the records of the global
798 mean surface air temperature and the atmospheric concentration of CO₂ over the period 1870–1991. Stern
799 and Kaufmann (2013) find that both natural and anthropogenic forcing cause temperature change
800 and also that temperature causes greenhouse gas concentration changes. The causal link between
801 temperature and CO₂ concentration is tested in (2013) using ice core data from 800,000 to 6,000 years
802 ago. The authors show strong evidence that CO₂ concentration Granger-causes temperature, as well as
803 that temperature Granger-causes carbon dioxide concentration. Triacca (2005) shows the limits of the
804 applications of GC in this context and proves that past observations of CO₂ concentration do not
805 significantly improve the predictability of current temperature. Further discussions on the application of
806 GC to these systems are available in the literature (Palus and Vejmelka 2007, Kampen 2010, Smirnov and
807 Mokhov 2015).

808 **3.4.4.2 Convergent cross mapping**

809 Sugihara et al. (2012) apply CCM and find causal evidence of the influence of climate forcing on
810 populations of sardines and anchovies in the California Current. Clark et al. (2015) further expand the
811 concept to include spatial variation in time-series data in order to accommodate for the case of limited

812 availability of data for a specific location. CCM has been applied also in the field of climate science. van
813 Nes et al. (2015) applied CCM and found a marked positive feedback effect from temperature variability
814 on greenhouse-gas concentrations. Tsonis et al. (2015) studied the association between cosmic rays and
815 global temperature in the 20th-century observational record without finding measurable evidence of a
816 causal effect linking cosmic rays to the overall 20th-century warming trend. The authors, however, do
817 find a significant causal effect of cosmic rays on short term variability in global temperatures. The
818 reproduction of the study by Luo et al. (2015) could not reproduce and confirm the findings.

819 **3.4.4.3 Transfer entropy**

820 TE has found limited application in the sustainability sciences. Kumar and Ruddell (2010) use the
821 technique to identify feedbacks between vegetation and climate components, using observations from a
822 network of monitoring towers across North America. The study finds that the relationship between
823 variability and information production leads to the emergence of ordered organization in the overall
824 system.

825 **4 Cause-effect analysis techniques in the context of QSA**

826 The ability for causal models to answer these questions in the context of QSA largely depends on whether
827 (1) the assumptions used by the technique are relevant in the context of QSA, and (2) whether it is viable
828 to construct the model considering data availability. Different causal models may exhibit strengths and
829 weaknesses for particular QSA applications depending on the relevance of the assumptions and the
830 availability of data, requiring the modelers to carefully evaluate the most suitable ones considering the
831 objectives and constraints of the study at hand.

832 **4.1 Evaluation of major assumptions of cause-effect analysis techniques for QSA**

833 **Error! Reference source not found.** lists the major assumptions used for cause-effect analysis
834 techniques introduced in section 3 [see also (Russo 2009)].

835 [Add Table 1 about here]

836 4.1.1 Linearity

837 The assumption of linearity needs to be carefully considered when applying the techniques in the context
838 of QSAs, and when interpreting the results of the analysis. The impossibility of building complex
839 nonlinear models does not fully impede to explain complex systems and provide interpretable causal
840 mechanisms. Linear models, in fact, can also support exploratory science and help identify trends and
841 dynamics in systems that are complex in reality [see also (Hofman et al. 2017) on predictive models
842 accuracy]. QSA typically deals with highly-nonlinear phenomena, thus the assumption of linearity would
843 question the strength of the causal-effect relationship measured assuming a linear relationship. The
844 application of QSA to the SDGs, for example, will likely require the analysis of complex non-linear
845 interconnected systems of policy interventions and effects. Understanding such actions and their
846 consequences under this condition requires incorporating all potential non-linearities into the causal
847 model.

848 In the context of SDGs, SDG number 14, which states “Conserve and sustainably use the oceans, seas and
849 marine resources for sustainable development”, includes the specific target of “reducing the loss of
850 marine species” (target 14.2 in the SDGs). The loss of marine species is determined by numerous factors
851 and by inter-species relationships that can only be partially grasped using linear relationships. When time-
852 series data is available, GC assumes linearity, while CCM is shown to be applicable to dynamic, non-
853 linear systems, thus avoiding the necessity to linearize relationships that are not linear in the real world.
854 The applicability of this technique in the context of QSA needs to be further tested. Therefore, ES, linear
855 OS, and GC have limited applicability for the QSAs of a system that involves significant nonlinear
856 processes.

857 The assumption of separability and additivity regards the application of OS for causal inference. Under
858 this assumption, the changes in the whole system under study can be understood as a sum of the changes
859 by single constituents of the system. This assumption may not always be verified in the context of QSA,
860 since individual constituents of a system that is being studied under a QSA may present specific

861 properties that would result in a different behavior of the whole system if combined with other
862 constituents. In the context of sustainability policy, for instance, government may decide to support a
863 cleaner technology by means of tax rebates, which in turn would typically have a beneficial effect on the
864 penetration of the technology in the market. Said rebates may be successful in promoting the diffusion of
865 this more environmentally desirable technology, while they may totally fail in some cases. This can be
866 due, for instance, to the strong and stable presence of a dominant alternative technology that has already
867 reached maturity, or to the lower cost of another alternative technology because of the contingent low cost
868 of raw materials, or to the irrational preference of consumers towards another preferred technology. The
869 consideration in the analysis of elements, such as market dynamics and irrationality of decision-making,
870 may bring upon the system unpredictable changes and unexpected behaviors that stem from the
871 interaction between these components over time. These interactions and changes could not be anticipated
872 by simply integrating the single elements into the analysis.

873 **4.1.2 Separability and additivity**

874 The assumptions of separability and additivity also relate to the assumption of no omitted variables and
875 no systematic measurement errors to which all techniques are bound. Due to the complexity and the type
876 interactions considered in QSA that often involve socio-economic transformations, it is likely that the
877 analysis may have one or more unaccounted factors. For example, SDG number 7 states “Ensure access to
878 affordable, reliable, sustainable and modern energy for all”. A goal like this cuts across various socio-
879 economic and technological variables of our society including population, income, energy technologies,
880 natural resource availability, price, social welfare, pollution, public health, legal systems, and their
881 changes and interactions with each other, to name just a few (see section 3.4.1, where energy
882 consumption is connected to the emission of pollutants such as SO_2 , NO_x). The existence and
883 directionality of such causal relationships were measured in most cases by means of GC (see section
884 3.4.1). When using such studies for the purpose of predicting future emissions of pollutants, however, the
885 existence of other intervening factors such as the existence of emission standards, regulations and their

886 level of stringency, or availability and affordability of emission mitigation technologies in those countries
887 may come into play, depending on their significance in explaining the relationships between energy
888 consumption and pollutant emissions. Similarly, ES, OS, CCM, and TE should possibly include these
889 factors if used to predict future changes.

890 **4.1.3 Stable-unit-treatment-value**

891 Earlier in this review, we have stressed the importance of extending the causal relationship between
892 variables from a single case or unit in a system to a population of individuals/units, thus to the entire
893 system under assessment. These criteria fall within SUTVA. The assumption is necessary to all
894 techniques considered, but is especially relevant for the causal interpretation of regressions. The
895 assumption of stability ensures that the causal factor is supposed to operate homogenously in the
896 population of interest. The size of the sample directly relates to the data availability for QSA (see section
897 4.2). A sufficient sample size is, thus, fundamental to generalize the findings for any of the techniques
898 that we presented. State-level policies on sustainability and their outcomes are limited by the fact that
899 there are only about couple of hundred states in the world and that the circumstances under which those
900 states operate, in terms of population, climate, endowment of wealth and resources, etc. are very different.
901 This problem is exacerbated when considering the fact that much of the sustainability-related policies
902 have been experimented mostly in high-income countries, leaving few empirical evidences associated
903 with low-income countries. This problem can be mitigated by the virtue of ‘natural experiments’ (Hsiang
904 et al. 2011, Gans et al. 2013, Hanna and Oliva 2015), while identifying a natural experiment that is
905 directly applicable to the question at hand is often challenging.

906 The behavior of the entire population cannot be understood by the behavior of individual constituents in
907 the presence of interactions among them (see section 3.2.1), which may display emergent properties at the
908 system’s level (Odum and Barrett 1971, Bar-Yam 1997). A failure to recognize that a certain system has
909 properties that are emergent can lead to a fallacious identification of a cause-effect relationship. In this

910 case, it is recommended to explore other approaches such as quantitative systems modelling, socio-
911 technical transition analysis, and initiative-based learning as elaborated in Turnheim et al. (2015).

912 4.1.4 Parameters and error term

913 In regression-based causal models, the error term is uncorrelated with the regressors, allowing the analyst
914 to interpret how much of the causal impact is escaping her control due to the factor \mathcal{E} . This assumption
915 applies to ES and OS techniques. This assumption for QSA means that all unknowns may be referred to
916 the error term, without the risk of missing, e.g. a third screening factor Z when analyzing variable X and
917 the related outcome Y . For the case of techniques that use time-series data, the core assumption is that a
918 variable X includes unique useful data to predict the state of a latent variable Y , so that variable X is
919 causally linked to Y . The assumption entails that no other variable should be relevant to describe such
920 cause-effect chain, thus the potential bias from unobservable variables can only be identified if all
921 potential other influential variables are considered.

922 Techniques that involve the use of time-series, namely GC, CCM and TE, can be used for causality
923 assessments under the assumption that the cause contains unique information about the effect under study
924 that could not be possibly obtained studying the time-series data of another potential cause. Such
925 assumption would mean that it could be possible to univocally relate effects to a single cause. Such
926 assumption may prove difficult to test in the general context of application of QSA, in which before
927 identifying a single cause-effect relationship a number of time-series should be simultaneously tested to
928 check for the potential information transfer and causal links between them. For this reason, the
929 applicability of these cause-effect analysis techniques should be tested in practical case studies, e.g.
930 related to the SDG. Practical applications would show the extent to which the assumption of causal
931 inclusion could be always demonstrated.

932 **4.2 Applicability**

933 Applicability of a technique should give a due consideration to the relevance of the assumptions that they
934 require. Even if the assumptions used in the presented cause-effect analysis techniques are relevant for the
935 particular problems with which a QSA is concerned, a technique may show limited applicability due to
936 other limitations, such as data availability. As seen in section 3.2.1, Rubin's model, for example, is an
937 ideal approach to cause-effect analysis. The model shows that causality can be inferred from a well-
938 designed randomized experiment (Holland 1986a). Even though such experimental design would be
939 preferable, the applicability of Rubin's model in the context of QSA is limited due to the data requirement
940 that any large-scale sustainability problem require to consider (see Table 2).

941 [Add Table 2 about here]

942 The data required to conduct an experiment in the fashion suggested by Rubin's approach is often
943 prohibitive, due to the difficulty of easily assigning individuals to treatment and control groups, and also
944 due to the difficulty of verifying alternative versions of the world that the counterfactual nature of Rubin's
945 model assumes. Unlike typical treatments considered in empirical studies, in the context of sustainability
946 policy, we have earlier noted that policy actions tend to evolve after they are launched, thus limiting the
947 possibility of guarantying that the sample data under study is stable throughout the experimental design.

948 Also, in Rubin's model only the factors that are treated in an experiment can be considered as legitimate
949 potential causes (Bhrolcháin and Dyson 2007). This implies that in all those contexts in which attributes
950 need to be taken into account the potential outcome model cannot be applied. This interpretation would
951 rule out personal attributes such as sex, or voluntary actions, such as deciding to start recycling waste, as
952 potential causes. In other words, there would be "no causation without manipulation" (Holland 1986b p.
953 959), so only factors that could, in principle, be manipulated should be considered as potential causes. By
954 ruling out factors that are not treated in an experiment from the pool of potential causes, the claim may
955 confuse the factors that *can be* causes with those that *can be shown to be* causes experimentally
956 (Bhrolcháin and Dyson 2007). Many phenomena that are thought to be potential causes in QSAs

957 sciences, in fact, cannot be manipulated. And even if an intervention of the analyst would be possible, it
958 would still be difficult, if not impossible, to find a counterfactual that could be selected as a control. Such
959 a specification would rule out experimentation from QSA, as well as from the social and natural sciences.
960 For this reason, the concept of causality is not dependent upon conditions of manipulability (Russo et al.
961 2011), and the capacity of an analyst to manipulate a cause is irrelevant to whether a factor is or could be
962 a cause in an experimental setting. Using a truly experimental design in QSA context comes with
963 challenges as we have highlighted. The absence of an experimental design like Rubin's does not render
964 the identification of causality impossible. We explored a set of techniques that can be used to assess
965 causality and sustain causal claims also in cases in which Rubin's model is unsuitable.

966 4.2.1 Observational studies and QSA

967 Methods based on observational data, such as matching techniques and causal regressions, under the
968 analyzed set of assumptions can provide an alternative means of assessing causality in the context of
969 QSA. We presented a number of examples that show that a well-defined causal regression allows for
970 cause-effect analysis even under the absence of an experimental design. The "no causation without
971 manipulation" criteria, again, would seem to rule out causal inference from observational studies (Angrist
972 and Pischke 2008). Over the years, many have questioned this standpoint. Glymour (1986), for instance,
973 finds the statement an unnecessary restriction, and objections can be found in the demography
974 (Bhrolcháin and Dyson 2007) and economic literature (Angrist and Pischke 2008). Pearl (2009) argues
975 that the essential ingredient for causation is the capacity of some variable to respond to variation in other
976 variables, regardless of the manipulation restriction imposed on the analyst. There certainly is, according
977 to Pearl, causation without manipulation, such as the gravitational force of the moon that causes tides [see
978 also Goldthorpe, (2001); (Pearl 2009)]. In the systems typically under assessment in QSA, manipulation
979 does not rule out, then, the use of observational studies. Moreover, observational data is increasingly
980 available and global efforts to collect and classify data are undergoing. Applications of OS should be
981 further tested.

982 Time-series techniques benefit from a vast availability of time-series data also in the QSA domain. GC
983 has found wide application to study the GDP-energy-pollution nexus (Wagner et al. 2016). When
984 interpreting the results of GC in the context of QSA, one should remember that the technique poorly
985 performs in the presence of non-linear, contemporaneous causal systems, and its results are ambiguous
986 when dynamic systems with weak to moderate coupling are under assessment (Sugihara et al. 2012). This
987 element does pose some factual limitations in the use of GC for QSA, also given the number of
988 interconnected systems that are typically under scrutiny.

989 The applicability of CCM should be further tested for QSA, since it would allow for the consideration of
990 dynamic, strongly coupled systems also under conditions of limited data availability. In the context of
991 sustainable energy of interest for SDG number 7, for instance, such approach could be beneficial to test
992 the relationship between renewable energy deployment and climate-change mitigation using the relatively
993 limited data available for renewable energy sources, which have been monitored only in the last two
994 decades. Similarly, TE could support such assessments, since it is easily applicable in the context of
995 complex dynamic systems; however, the limited application in real cases does not allow for total
996 appreciation of the full potential of TE for QSA at the current stage of knowledge.

997 In order for cause-effect analysis techniques to be applicable for QSA, causal explanations should not be
998 derived with statistical methods alone (Goldthorpe 2001). The role of the analyst in the form of
999 background knowledge and theories, otherwise considered a subject-matter input, is key to design a
1000 causality study for QSA. To this end, all methods come with limitations and in all cases the *caveat* of the
1001 presence of strong assumptions is valid, as we have pointed out for each method in the previous section.

1002 In some cases, little evidence is available to the analyst when the claim is made that a causal model
1003 accurately estimates causal effects, and sometimes causal models can be wrong. We hold here the
1004 definition that of Berk et al. (2013) coined for SEM, stating that a causal model is “a quantitative theory
1005 of how the data were generated, in which a statistical formalization for random variables is combined
1006 with a causal account derived from subject-matter knowledge”. For QSA, the statistical properties of the

1007 observed data model and the assumptions need to be carefully scrutinized before inferring causal
1008 relationships in order to avoid spurious results (Hlaváčková-Schindler et al. 2007). Global tests of model
1009 fit (e.g. the likelihood ratio chi-square test) should be combined with local tests [e.g. partial correlations
1010 and tetrad tests (Bollen and Ting 2000)], which allow for a more accurate model diagnosis and fine-
1011 tuning (Bollen and Pearl 2013). Also, more replications of causal models should be then combined as
1012 needed in different settings and among different populations in order to strengthen the causal claims
1013 (Brand and Thomas 2013).

1014 **4.2.2 Dynamic and temporal inconsistencies**

1015 The causal models we described typically deal with historical data, and try to map causal mechanisms
1016 based on relationships between inputs and outcomes that have typically matured over a stretch of time in
1017 the past. However, the preferences of decision-makers measured at one point in time are not fixed, and
1018 they are not necessarily representative of future preferences. The so-called dynamic or temporal
1019 inconsistency (Thaler 1991, Loewenstein and Prelec 1992) refers to the apparent disagreement between
1020 decisions taken or preferences expressed at a certain time, and that change at a later stage. This
1021 incongruence of behavior determines a situation in which plans that are made (or policy that are
1022 developed) at one point in time may not attain the same level of outcome later (Pearce et al. 2003). This is
1023 true for the case of individuals, and even more for the case of societies that usually satisfy weaker
1024 rationality and congruence conditions than individuals (Pearce et al. 2003). In the context of QSA, the
1025 issue of dynamic inconsistencies is especially relevant, as the temporal dimension involved tends to be a
1026 longer term future, over which causal relationships may change. The existence of dynamic inconsistency
1027 indicates that policy recommendations based on a QSA that uses a causal relationship need to be re-
1028 evaluated over time to fully account for the changes in preference over time.

1029 **5 Outlook: causality for quantitative sustainability assessment**

1030 The ability to identify causality between policy instruments and sustainability performance indicators,
1031 including those listed under the SDGs, provides decision makers with a powerful tool. We surveyed a

1032 number of cause-effect analysis techniques and their applications in the field of sustainability (in section
1033 3, and also see Appendix A for a synthesis). Our review demonstrates that in the field of QSAs causality
1034 could provide a means to understand phenomena and their causes, as well as to investigate the effective
1035 policy measure to achieve desired outcomes. The use of cause-effect analysis techniques has important
1036 benefits also in analyzing the effect of a policy option (e.g. the level of air pollution abatement due to the
1037 introduction of road space rationing in a city). Such techniques can be used by decision makers to
1038 prioritize policy options, and understand the expected outcomes and potential unintended consequences.

1039 We used SDGs to contextualize causal research and its applicability in QSA. In this context, we showed
1040 the challenges of understanding how various processes in the systems under study by QSA are connected
1041 and how specific policy or management actions can help address SDGs. Our review also discussed a
1042 number of caveats when applying cause-effect analysis techniques to QSA. The application of cause-
1043 effect analysis techniques is still a challenge in the field of sustainable development. Existing are confined
1044 to limited idealistic and isolated cases that are still far from the breadth of analysis that is required by the
1045 SDGs. Existing frameworks, as they stand, therefore, may offer limited insights for the questions as
1046 complex as SDGs. Overcoming such barriers would require a cross-disciplinary effort to develop an
1047 operational framework for quantifying the sustainability consequences of policy actions addressing the
1048 needs of QSA, discussed in this review. In the meantime, it is inevitable that QSA practitioners will have
1049 to make use of the imperfect information on causality from e.g., mechanistic models or from the use of
1050 the cause-effect analysis techniques presented in this review under the assumptions used and the
1051 limitations associated with them.

1052 The application of causality for QSA also poses a number of challenges that relate to both the
1053 assumptions and the data requirement. Assumptions need to be tested, and the related uncertainties should
1054 be analyzed in order for a cause-effect analysis to be valid (Maxim and van der Sluijs 2011). The results
1055 should be carefully interpreted in light of the assumptions.

1056 In relation to data availability, we discussed both experimental and observational techniques. Although
1057 experimental studies are always the preferred option, they are often impractical, and analysts may be
1058 reliant on observational studies alone. Formal experiments are of limited application for many of the most
1059 pressing questions of social relevance such as those directly related to climate change, large-scale
1060 agricultural intensification or habitat loss (Stephens et al. 2014). When it comes to irreversible, large-
1061 scale changes that SDGs and corresponding policy actions are interested in, obviously, experiments are
1062 neither practical nor desirable. Furthermore, deriving an unbiased estimate using indirect approaches,
1063 such as natural experiments, comes with its own challenges and limitations (Cucurachi and Suh 2015).
1064 Adequate non-experimental settings are, then, required to avoid these questions remaining elusive in the
1065 absence of experimental evidence. Sufficient survey data and time-series data are available for regression-
1066 based causality and time-series cause-effect analysis techniques, respectively, and new methodological
1067 developments, such as CCM and TE, allow for dealing with causality under those circumstances in which
1068 the analyst faces dearth of data.

1069 Non-experimental cause-effect analysis techniques are powerful but do have limitations and need to
1070 accurately be interpreted before causal claims can be safely held to the test. Robust and unambiguous
1071 results are difficult to obtain, and many causal claims are yet to be tested with an experimental or quasi-
1072 experimental design. Simple correlation at times is taken as a direct measure of the strength of the causal
1073 mechanism, or a certain *driver* X is identified as determinant for a certain response Y (e.g. international
1074 trade as a driver of biodiversity loss) without testing the relationship using a formal cause-effect analysis
1075 technique. The latter does not exclude any complex model from providing valuable information to
1076 decision makers, but only suggests caution when causal claims are not supported by experimental models
1077 or carefully designed causal models fitted on observational data with all the related assumptions and
1078 limitations.

1079 We acknowledge that the framework of hypotheses, assumptions, limitations and the boundaries of the
1080 causal analysis matter when claiming the existence of a causal relationship, or when an analysis aims at

1081 verifying the existence of causal mechanisms. Still, new avenues of research can open opportunities for
1082 the development of improved cause-effect analysis techniques that build upon the body of knowledge that
1083 we have analyzed in this review.

1084 We highlighted the difficulty of framing cause-effect research at the country level, due to the limited
1085 number of countries available as a sample, and due to the sheer differences that exist among them. A
1086 more promising level of analysis could have cities, instead, at the core. Socio-technical transitions that
1087 work at a single city level can be more easily compared with other cities with similar characteristics. To
1088 this end, the phenomenon of urban experimentation (Bulkeley and Broto 2013, Rijke et al. 2013,
1089 Voytenko et al. 2016) that has been gaining momentum in the last years does have the potential to support
1090 change at the global level in the context of SDGs (see also SDG number 9 on resilient cities). New
1091 datasets are being compiled based on the local experience of cities, and further efforts should be
1092 supported to collect and categorize this information. These data can be used to set up causal quasi-
1093 experimental and observational designs to support decision-making for sustainability and the SDGs.

1094 The increased availability of data to which urban experimentation contributes joins the possibility to
1095 access and use large data sets. The challenges to causally analyze the so-called Big Data to reveal
1096 patterns, trends, and associations, especially related to human behavior and interactions, are enormous
1097 (Shiffrin 2016). The task is daunting and requires efforts across multiple disciplines, from the economics
1098 to all the sub-disciplines of the sustainability sciences (Athey 2017). Machine learning techniques, among
1099 others, have been suggested as a promising joint topic from which such effort could begin (Varian 2016).

1100 QSA sciences, such as industrial ecology, should combine the benefits of an increased availability of data
1101 (Xu et al. 2015) with the benefits of understanding causality. Qualitative approaches such as causal loop
1102 diagrams (Asif et al. 2015, Laurenti et al. 2015, Efrogmson et al. 2016) should be combined with
1103 quantitative techniques, and also QSA scientist should reach to other disciplines to contribute to perfect
1104 the existing cause-effect analysis techniques. Until new techniques and a new framework for causality in
1105 QSA would be available, scientists would still have to resort to alternative techniques (e.g. agent-based

1106 modelling) that, although useful and at times sufficient for single assessments, cannot provide a
1107 substantive basis for causal inference at the level required by the SDGs.

1108 In the sub-field of LCA (Hellweg and Mila i Canals 2014), causality is of particular interest in the context
1109 of the consequential approach to LCA (Zamagni et al. 2012). Following the consequential approach, the
1110 LCA analyst defines changes in a product system and models how the physical and social processes will
1111 be triggered by such changes in the system (Earles and Halog 2011). In short, consequential LCA
1112 assumes that changes to some parts of the life cycle inventory system lead to a series of consequences
1113 through chains of cause–effect relationships (Curran et al. 2005). Concepts borrowed from economic
1114 modelling, such as elasticities of supply and demand or general and partial equilibrium models, have been
1115 proposed in existing consequential LCA studies or have been recommended for inclusion to simulate
1116 responses to changes in the system (Ekvall and Andrae 2006). Practical applications that include these
1117 theories in LCA are still limited (Suh and Yang 2014), and only recently alternative solutions have been
1118 proposed, for instance using optimization techniques to anticipate changes in a system (Duchin and
1119 Levine 2011). We add to the research agenda of the consequential LCA community the necessity to study
1120 cause-effect relationships by means of causality theory and methods, thus contributing to increasing the
1121 value of the results.

1122 The adoption of causality in all QSAs and the necessity to control causal dynamics and mechanisms
1123 requires involvement of experts from a variety of disciplines that can help disentangle those mechanisms
1124 and design appropriate causal studies. Collaborations among multiple disciplines will help development
1125 of new computational models, methods, and tools to tackle the various aspects of sustainability (Gomes
1126 2009, Marvuglia et al. 2015). Such effort will progressively allow for understanding of the
1127 interconnections between SDGs and the results of QSAs beyond the sole use of indicators (Mirshojaeian
1128 and Kaneko 2012).

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Table 1. Set of assumptions of cause-effect analysis techniques

Assumption	Definition	Cause-effect analysis technique				
		ES*	OS	GC	CCM	TE
Linearity	Causal relationships are linear in the parameters and in the explanatory variable X and the response variable Y .	x	(x) [†]	x		
Separability and additivity	The response variable Y is the sum of explanatory variables X and the errors \mathcal{E} .		x			
No omitted variables and no systematic measurement errors	The analyst assumes that the factors considered in the analysis sufficiently represent the causal relationship at stake, and the measurement errors in the variables are random (i.e., not systematic) and are within a tolerable range. Under the hypothetical condition that expected \mathcal{E} is equal to zero, the causal effect Y is explained by the explanatory variables X s.	x	x	x	x	x
Stable-unit-treatment-value-assumption	The potential outcome of one individual of a population is not affected by the treatment applied to another individual of the population.	x	x	x	x	x
No correlation within and between explanatory variables and	Explanatory variables and errors are not correlated with each other.	x	x			

errors						
Cause inclusiveness	A cause contains unique information about an effect not available elsewhere.			x	x	x

* ES = Experimental design based on Rubin’s model; OS = Observational designs based
 matching and regression techniques; GC = Granger-causality; CCM = Convergent Cross
 Mapping; TE = Transfer entropy. † In the case of non-linear regression, linearity assumption
 does not apply to OS

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Table 1. Synthesis of cause-effect analysis techniques for QSA research

Cause-effect analysis technique	Data requirements	Advantages	Disadvantages
ES*	High	<ul style="list-style-type: none"> • Most trusted approach • Quantifiable strength of the causal relationship 	<ul style="list-style-type: none"> • Cost of implementation • Complexity of systems under analysis • Limited possibility of integrating assumptions in QSA • Limited possibility of replicating a study
OS	Medium	<ul style="list-style-type: none"> • Good alternative to experimental designs • Ease of application • Ease of access to data 	<ul style="list-style-type: none"> • Risk of data manipulation • Limited possibility of randomization for certain variables • Limited possibility of generalizing findings from sample to the full population
GC	Medium	<ul style="list-style-type: none"> • Extensive literature • Ease of application • Ease of access to time-series data 	<ul style="list-style-type: none"> • Inapplicability in the presence of non-linear, contemporaneous causal systems • Ambiguous results for dynamic systems with weak to moderate coupling

CCM	Low	<ul style="list-style-type: none"> • Short time-series data • Applicability to dynamic systems • Applicability to non-linear, contemporaneous causal systems 	<ul style="list-style-type: none"> • Limited application to contexts with multiple causal variables • Untested application in the sustainability realm
TE	Medium	<ul style="list-style-type: none"> • Applicability to dynamic systems • Easy to model 	<ul style="list-style-type: none"> • It is only a measure of observed (conditional) correlation rather than direct effect • Untested application in the sustainability realm

* The acronyms in the table refer to ES = Experimental design based on Rubin's model; OS = Observational designs based on matching and regression techniques; GC = Granger Causality; CCM = Convergent Cross Mapping; TE = Transfer entropy